
Author Correction: A soft robot that adapts to environments through shape change

Correction to: *Nature Machine Intelligence*
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 Check for updates

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It has come to the authors' attention that the claims in the paper about automatically optimizing the robot's body shape and control policy in simulation before transferral to the physical robot are unsupported by the data. All other data and claims related to the physical robot remain intact. We have removed the automatic optimization data and made edits and deletions throughout the article. See Supplementary Information for a list of changes and an uncorrected, original version of the article for reference.

Additional information

Extended data is available for this paper at <https://doi.org/10.1038/s42256-024-00814-w>.

Supplementary information The online version contains supplementary material available at <https://doi.org/10.1038/s42256-024-00814-w>.

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