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Cells solved the Gibbs paradox by learning to contain entropic forces

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As Nature's version of machine learning, evolution has solved many extraordinarily complex problems, none perhaps more remarkable than learning to harness an increase in chemical entropy (disorder) to generate directed chemical forces (order). Using muscle as a model system, here I describe the basic mechanism by which life creates order from disorder. In short, evolution tuned the physical properties of certain proteins to contain changes in chemical entropy. As it happens these are the "sensible" properties Gibbs postulated were needed to solve a paradox that has intrigued and challenged scientists and philosophers for over 100 years.

Text

In 1876 J.W. Gibbs identified a paradox in his chemical thermodynamic treatment of entropy¹ that has confounded scientists from Boltzmann to Einstein and that remains an intriguing puzzle to this day²⁻⁵. There is presently no one explicit solution to the paradox, and it has been suggested that "the multiplicity of solutions proposed...[implies] that there are different ways of conceiving the foundations of thermodynamics"². Biological systems that have evolved to contain entropic forces^{6,7} provide a model system for studying this paradox, which I use here to show that the multiplicity of proposals are not distinct concepts but rather elements of a single explicit solution.

The paradox applied to a two-state chemical reaction

A version of the Gibbs paradox is illustrated in Fig. 1. Figure 1A is a kinetic scheme for a chemical reaction in which a molecule reversibly isomerizes between two chemical states, B and Y, differing only in color. In state B, the molecule is blue, and in state Y, the molecule is yellow. The molecule switches between these states with forward, f_+ , and reverse, f_- , rates. If at time $t=0$ a system contains 10 such molecules all in state B (Fig. 1B, left), then at a later time $t > \tau = \frac{1}{f_+ + f_-}$ the system will equilibrate with molecules distributed (equally if $f_+ = f_-$) between states B and Y (Fig. 1B, right). In a solution containing many molecules, this reaction appears as a blue solution that irreversibly turns green (Fig. 1C, left to right).

Figure 1C resembles experiments in which two drops of different colored dyes are placed into a glass of water and mix spontaneously and irreversibly through diffusion; only here the spontaneous change in color occurs through a two-state chemical reaction. Because in both cases, an irreversible mixing of colors is energetically driven by an increase in system entropy, here I refer to the equilibration of the chemical reaction in Fig. 1C as "mixing".

The spontaneous change in color in Fig. 1C is energetically driven by the entropic contribution, ΔS , to the free energy for the reaction in Fig. 1A, where ΔS is defined independent of the colors of the two states so long as the difference, d , between them (here a wavelength) is distinguishable. When the two states become indistinguishable ($d=0$), the reaction no longer occurs because there is only one state (one color). At this point ΔS abruptly vanishes. The paradox is that a subtle change in the difference between states (from d being barely detectable to $d=0$) has unexplained, discontinuous energetic consequences.

Most proposed solutions to this paradox are based on arguments invoking a mutable ΔS^2 . Maxwell argued that ΔS is defined by the mind that perceives molecular differences (e.g., Maxwell's demon). Gibbs argued that ΔS is only defined by sensible properties. Not surprisingly, Planck argued that ΔS requires finite differences, d_{crit} , between molecular states, claiming "Chemical differences between... two substances in general cannot be represented by a continuously variable quality; and that we instead have to do with discrete distinctions... This

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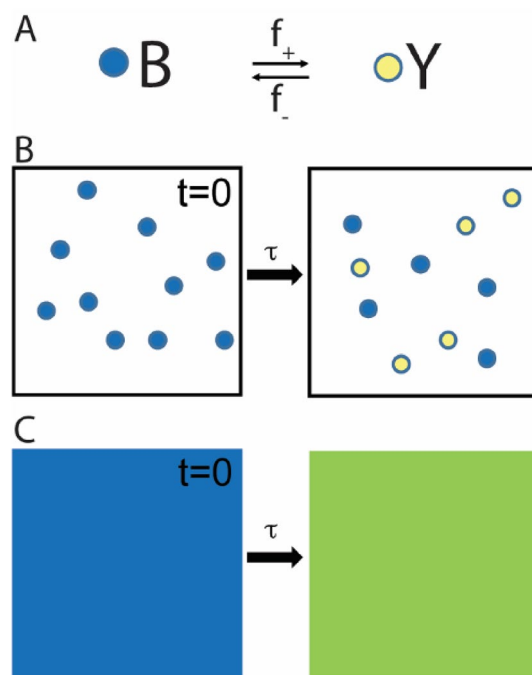


Figure 1. Entropy of mixing in a two-state chemical model. (A) A chemical scheme of a molecule that isomerizes with forward, f_+ , and reverse, f_- , rates between two states that differ only in color. State B is blue, and state Y is yellow. (B) At $t=0$, a closed system contains 10 such molecules all in state B (left panel). With a relaxation time constant, τ , the entropic contribution to the free energy for the reaction in panel A irreversibly (single right arrow) drives the system to a state characterized by an equilibrium mixture of states B and Y (right panel). (C) In a bulk solution, the reaction in panel B appears as a solution that irreversibly changes color from blue to green.

circumstance creates a principal opposition between chemical and physical properties since the latter must always be regarded as continuously variable².

The common assumption, made here by Planck and elsewhere by others, that entropic changes must be continuously variable is the basis for the infamous arbitrary division by $N!$ employed by Boltzmann in his analysis of the Gibbs paradox (see below)². However, for small ensembles of proteins in biological systems neither chemical nor physical properties are continuous, and as shown here, by considering the discrete changes in system entropy associated with discrete chemical steps, Boltzmann's $N!$ term cancels, and both Gibbs' sensible properties and Planck's d_{crit} are explicitly defined.

Biological systems like muscle have evolved to contain entropic forces within cells by tuning proteins to optimize their sensible properties and d_{crit} ; as such, they serve as model systems for formally developing these concepts. Using muscle as a model system, I define the energy of mixing for the reaction in Fig. 1, which is extensive over the reaction (see below). Next, I describe a mechanism for un-mixing (a mechanistic difference, d , between states) inspired by the chemistry of muscle contraction. Finally, I calculate the d -dependent energy required for un-mixing, providing a unifying description of molecular mechanics and emergent thermodynamics.

The energy of mixing

According to Boltzmann, the entropy, S , of a system is $k_B \ln \Omega$, where Ω is the number of microstates accessible to the system. Within a given state, $\{N_B, N_Y\}$, of the system in Fig. 1B, the number of microstates is $\frac{N!}{N_B!N_Y!}$, where N_B and N_Y are the number of molecules in states B and Y, and $N = N_B + N_Y$. With a single chemical step from blue to yellow, the number of microstates within this new state $\{N_B - 1, N_Y + 1\}$ becomes $\frac{N!}{(N_B - 1)!(N_Y + 1)!}$. The change in system entropy, ΔS , with a chemical step from $\{N_B, N_Y\}$ to $\{N_B - 1, N_Y + 1\}$ is

$$k_B \ln \frac{N_B!N_Y!}{(N_B - 1)!(N_Y + 1)!}$$

(note the $N!$ terms cancel), and according to Boltzmann

$$\Delta S = k_B \ln \frac{N_B}{N_Y + 1}.$$

According to Gibbs, the entropic contribution to the free energy that drives the mixing reaction (Fig. 1) is then

$$T\Delta S = k_B T \ln \frac{N_B}{N_Y + 1}. \quad (1)$$

Summed over multiple chemical steps, the change in entropy is extensive over the reaction.

Because a color change has little physical impact, here I consider a version of the two-state scheme in Fig. 1 in which the difference between states is mechanical. Specifically, I consider a two-state chemical reaction where the difference between states is a measurable displacement, d (Fig. 2A).

A binary mechanical system

Figure 2 describes a binary mechanical system that accounts for many mechanical, chemical and energetic aspects of muscle contraction^{7,8}. In Fig. 2A, actin filament binding induces a conformational change in myosin (a structural lever arm rotation) that displaces the actin filament a distance d ^{9,10}. For continuity with Fig. 1, a hypothetical fluorophore bound to myosin changes color from blue to yellow when myosin binds actin (Fig. 2A). Focusing on entropic forces, here I assume that the actin-myosin binding free energy, ΔG° , is zero (i.e., $f_+ = f_-$).

Figure 2B is the same mixing reaction illustrated in Fig. 1B, only here myosin molecules that are attached to a fixed surface move an actin filament attached to a moveable surface a distance, d , with each discrete chemical step from B to Y. In other words, an increase in system entropy generates directed movement. This entropically-driven system contraction can be reversed by physically pulling on the system to expand it. The change in external force, ΔF_{ext} , required to mechanically pull the system from green (a mixture of yellow and blue) back to blue, can be calculated from changes in both molecular, ΔF_1 , and entropic, ΔF_S , forces.

In single molecule mechanics studies, we have shown that a single chemical step from B to Y displaces a spring of stiffness κ_{sys} , generating force, $\kappa_{sys}d$,^{10–12} where d can be experimentally measured and controlled by genetically engineering different myosin lever arm lengths¹³. We have also shown^{10,14} that a chemical reversal of this step decreases force

$$\Delta F_1 = -\kappa_{sys}d. \quad (2)$$

A single system spring of stiffness κ_{sys} provides a useful construct for uniting molecular force generation and system forces. As illustrated in Fig. 2C, one end of a system spring is extended or shortened by reversible chemical steps, d (bottom), while the other end (top) of the spring equilibrates with a macroscopic (e.g., entropic) force⁷.

When the system in Fig. 2B (right) is pulled to generate force $\Delta F_{ext} = -\Delta F_1$ (Fig. 2C, left), the system responds with a single molecule step from state Y to B (Fig. 2C, left to right) that reverses ΔF_{ext} (Eq. 2). This decrease in system force, ΔF_1 , with a single molecule step is the driving force for the un-mixing step. However, the system does not equilibrate with a single molecule step; it equilibrates with a chemical relaxation of the system. Upon equilibration the increase in entropy associated with an ergodic transition from {5,5} to {4,6} is balanced against an increase in entropic force, F , that is defined by the equilibrium free energy equation for the reaction in Fig. 2A:

$$\Delta G^\circ - T\Delta S + Fd = 0. \quad (3)$$

Here Fd is the work performed by a single step d against the system force, F , and $T\Delta S$ is defined by Eq. (1). Assuming $\Delta G^\circ = 0$, the equilibrium entropic force is

$$F = \frac{k_B T}{d} \ln \frac{N_B}{N_Y + 1}. \quad (4)$$

Consistent with Eq. (4), we have shown experimentally¹⁵ that when a force, F , is applied to an equilibrium muscle system in which the actin-myosin binding affinity is chemically diminished, the observed distribution of states changes with F as $\frac{N_Y}{N_B} = e^{-\frac{Fd}{k_B T}}$, demonstrating that, consistent with Eq. (4), an equilibrium mixture of force generating myosin molecules can be unimixed by increasing F . According to Eq. (4), the change in entropic force with a change in system state from $\{N_B, N_Y\}$ to $\{N_B + 1, N_Y - 1\}$ is

$$\Delta F_S = \frac{T\Delta\Delta S}{d} = \frac{k_B T}{d} \ln \frac{(N_B + 1)(N_Y + 1)}{(N_B)(N_Y)} \quad (5)$$

which ranges at large N from approximately zero when fully mixed ($N_B = N_Y$) to approximately $\frac{k_B T}{d} \ln 2$ when fully unimixed ($N_B = N - 1$ and $N_A = 1$). Equation 4 describes the force, F , at which the system in state $\{N_B, N_Y\}$ is at equilibrium, which occurs when the reaction free energy is zero Eq. (3). Because the reaction free energy is defined as the change in system free energy with a change in the extent of the reaction, F in Eq. (4) is defined by a change in entropy with the extent of the reaction, or a reaction entropy, ΔS . The system equilibrates in state $\{N_B + 1, N_Y - 1\}$ at a different F and a different reaction entropy, ΔS . The difference between these forces, ΔF_S , is described by a difference between reaction entropy ΔS values, and thus is a change in the reaction entropy, $\Delta\Delta S$.

According to continuous, near-equilibrium definitions of entropic changes, small external increments in the system force, $\Delta F_{ext} = \Delta F_S$ (Eq. 5), reverse the mixing reaction along a smooth isotherm (Eq. 4). However, in a discrete physical chemical analysis, a transient change in mechanical force, $-\Delta F_1$ (Eq. 2), physically drives the un-mixing step. Combined, the change in external force required to drive the un-mixing reaction forward, $-\Delta F_1$, against the increased entropic force, ΔF_S , is $\Delta F_{ext} = \Delta F_S - \Delta F_1$, or

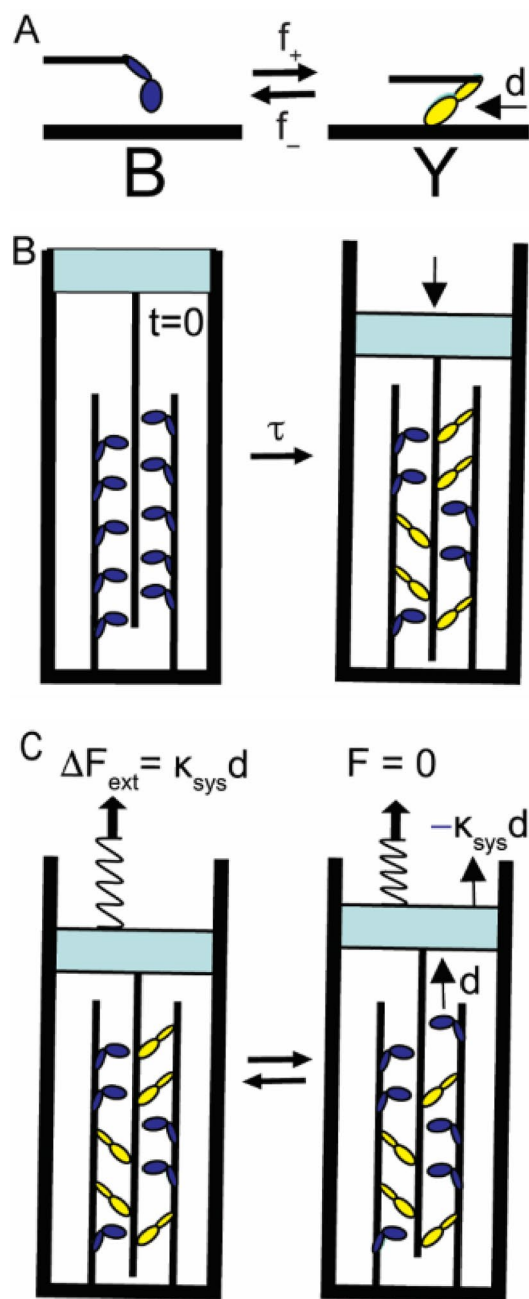


Figure 2. Entropy of mixing in a binary mechanical system. (A) A chemical scheme of a molecule that isomerizes with forward, f_+ , and reverse, f_- , rates between two states that differ by a mechanical displacement, d . State B is a myosin detached from actin. State Y is a myosin bound to actin. The transition from state B to Y displaces actin relative to myosin. (B) At $t=0$, a closed binary mechanical system contains 10 such molecules all in state B (left panel). With a relaxation time constant, τ , the entropic contribution to the free energy for the reaction in panel A (single right arrow) drives the system to a state characterized by an equilibrium mixture of states B and Y (right panel). The net increase in the number of molecules in state Y results in a net displacement of the actin filament (attached to a freely movable wall) relative to myosin (attached to a fixed wall). (C) An equilibrium binary mechanical system in state $\{5,5\}$ at $F=0$ (panel B, right) is pulled in a direction that reverses the displacement in panel B, generating force $\Delta F_{\text{ext}} = -\Delta F_1$ in a system spring of stiffness κ_{sys} . The system responds with an average transition of one molecule from Y to B that reverses ΔF_{ext} resulting in $F=0$. Entropic force generation follows with ergodicity.

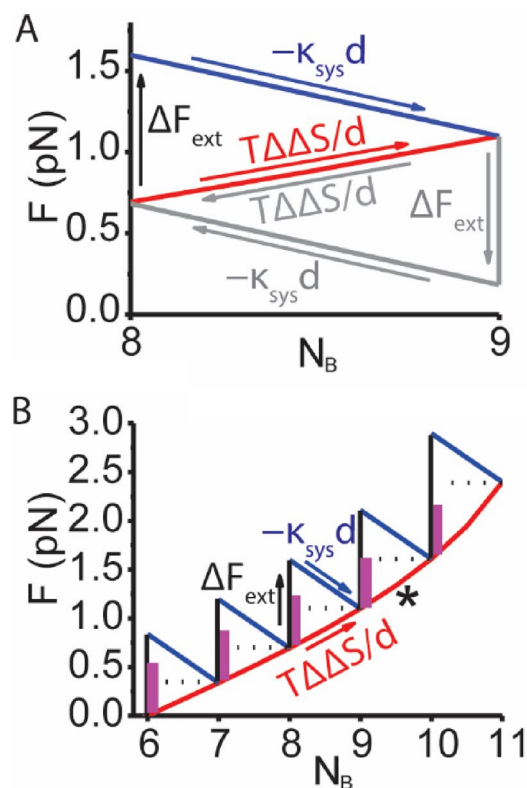


Figure 3. Forces required to unmix a binary mechanical system ($\kappa_{\text{sys}} = 0.125$ pN/nm and $d = 4$ nm). **(A)** A binary system like that in Fig. 2C only with $N = 11$ molecules is pulled to generate the force, ΔF_{ext} , required to unmix the system from equilibrium state $\{8,3\}$ to $\{9,2\}$. The system responds with a decrease in mechanical force, $\Delta F_1 = -\kappa_{\text{sys}}d$ (blue arrow) and an increase in entropic force, $\Delta F_S = T\Delta\Delta S/d$ (red arrow) associated with that step. The overall transition starts and ends along the isotherm (Eq. 4, red line) **(B)** A series of unmixing steps like that in panel A illustrates how mixing stalls (asterisk) when the finite molecular driving force $-\kappa_{\text{sys}}d$ (maroon bar) equals the entropic resistive force $T\Delta\Delta S/d$ (horizontal dashed lines).

$$\Delta F_{\text{ext}} = \frac{T\Delta\Delta S}{d} + \kappa_{\text{sys}}d. \quad (6)$$

Figure 3A illustrates this tripartite sequence of mechanochemical events for a system containing $N = 11$ molecules. When the system force is increased, ΔF_{ext} , by externally pulling on the system (Fig. 3A, up arrow), the system responds with a chemical step from state $\{8,3\}$ to $\{9,2\}$, which occurs with both a decrease in molecular mechanical force, $-\kappa_{\text{sys}}d$ (Fig. 3A, blue arrow), and an increase in entropic force, $\frac{T\Delta\Delta S}{d}$ (Fig. 3A, red arrow), resulting in a new equilibrium force along the isotherm (Eq. 4, red line). The chemical reversal of the above process (Fig. 3A, gray arrows and text) defines a finite minimum work loop around a single chemical step.

The total driving force for un-mixing is $\kappa_{\text{sys}}d - T\Delta\Delta S/d$, which means that when $\kappa_{\text{sys}}d = T\Delta\Delta S/d$, un-mixing is physically not possible. This defines a finite minimum difference between states of

$$d = d_{\text{crit}} \equiv \sqrt{\frac{T\Delta\Delta S}{\kappa_{\text{sys}}}}. \quad (7)$$

Equation 7 is more than simply an equilibrium condition. It describes the point at which a chemical equilibrium is unaffected by work performed on the system, ΔF_{ext} . Beyond this point, when ΔF_{ext} exceeds that defined by Eq. (6), ΔF_{ext} becomes a passive force that is uncoupled from chemistry (it has no effect on Eq. (7) and incapable of further unmixing the system). While pulling on the system harder to generate forces beyond ΔF_{ext} (Eq. 6) might forcibly detach molecules or even tear the system apart (chemically irreversible processes), the reversible un-mixing reaction is not mechanically driven by ΔF_{ext} ; it is mechanically driven by $-\kappa_{\text{sys}}d$, which is defined by finite molecular parameters. In other words, the finite molecular difference, d_{crit} , postulated by Planck, is related to the sensible property, $-\kappa_{\text{sys}}d$, postulated by Gibbs through a discrete change in system entropy (Eq. 7).

Because $T\Delta\Delta S/d$ increases from 0 to $\frac{k_B T}{d} \ln 2$ with unmixing, Eq. (7) indicates that a reaction can be unmixed to some extent even with a relatively small d . This is illustrated in Fig. 3B where increments of ΔF_{ext} unmix the reaction along the isotherm (Eq. 4) until $d = d_{\text{crit}}$ (Fig. 3B, asterisk) beyond which point the reaction cannot physically be further unmixed.

When $d < d_{crit}$ entropic force dominates and mixing occurs spontaneously and unstoppably against a relatively small mechanical force, $\kappa_{sys}d$. At the other extreme, when $d \gg d_{crit}$, there is no chemical contribution to mixing or unmixing (Eq. 6), and at this molecular mechanical limit the reaction is driven forward and backward by external mechanical steps alone, $\Delta F_{ext} = \Delta F_1$.

Conclusion

The above analysis provides a solution to the Gibbs paradox as it pertains to a binary mechanical system (Fig. 2B). The analysis implies that only at the discrete finite limit of chemical steps can we define changes in both molecular and entropic forces (Fig. 3A) that together unify molecular mechanics (top descending limb) and emergent thermodynamics (bottom ascending limb). Only at this discrete limit can we define the molecular mechanical force, $-\kappa_{sys}d$, (Fig. 3A, negative slope) that drives a chemical step against the entropic force of mixing, $T\Delta\Delta S/d$, (Fig. 3A, positive slope). And only at this discrete limit do we recognize that un-mixing is physically not possible when $-\kappa_{sys}d$ (the driving mechanical force) is less than $T\Delta\Delta S/d$ (the resistive entropic force).

Equivalently, un-mixing is physically not possible when the mechanical energy, $-\kappa_{sys}d^2$, is less than the entropic energy, $T\Delta\Delta S$; as such $-\kappa_{sys}d^2$ can be viewed as a finite physical (sensible) container of $T\Delta\Delta S$. When the container is large, it can hold large amounts of $T\Delta\Delta S$. When the container is small, only small amounts of $T\Delta\Delta S$ can be held in a system with the excess irretrievably spilling out into the universe. In Fig. 3B, the maximum extent of unmixing changes with the size of the container (Fig. 3B, maroon bar). Here, the approach to indistinguishable states (as d becomes small) is continuous. The container (the capacity to physically measure, use or reverse $T\Delta\Delta S$) becomes infinitesimally small ($\kappa_{sys}d^2$ gets small) as the two states become infinitesimally similar, and when d becomes zero, there is at once both no container and nothing to contain.

Through all processes and at all scales across the universe entropy increases, and this increasing disorder can be locally ordered (measured, used, or reversed) only when placed in a proper container. The primordial soup consisted of chemical reactions dominated by thermal energy and increasing entropy, and despite the exacting physical relationships required (Eqs. 6 and 7), biological systems have evolved highly effective mechanisms for containing within cells the $T\Delta\Delta S$ for certain reactions. Thus, it is no surprise that the chemical reaction that drives muscle contraction informs us of these relationships.

Large containers ($d \gg d_{crit}$) that dominate entropy flip the agency of a reaction ($\Delta F_{ext} = \Delta F_1$, with no chemical forces). Because the primordial soup contained a paucity of directed external forces, ΔF_{ext} , available to order cells but an abundance of increasing entropy, $T\Delta\Delta S/d$, available to be ordered by them, catabolic reactions evolved as unidirectional chemical forces (e.g., $\frac{T\Delta\Delta S}{d}$) that drive unidirectional changes in surrounding forces, ΔF_{ext} ($d \approx d_{crit}$) not the other way around ($d \gg d_{crit}$). This emergent perspective is the antithesis of the molecular (corpusecular) mechanic myth^{16,17} that gears and springs from the primordial soup were pieced together using rational mechanics ($\Delta F_{ext} = \Delta F_1$). Paraphrasing Gibbs, we will never find in molecular biology an a priori foundation for the principles of biological function.

The arguments above are clearly not limited to muscle force. Biological forces exist on many different scales (filaments, organelles, cellular, multi-cellular) and in many different forms (ion gradients, cell tension, cell crowding, osmotic pressure, surface tension), and any one of these forces has the potential to contain entropy in many different forms within biological systems. The above thermodynamic relationships (Fig. 3A) transform our understanding of how muscle works^{7,8} and have broad implications for both natural and mimetic biology.

Data availability

All data are available in the main text.

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Competing interests

The author declares no competing interests..

Additional information

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