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OPEN Author Correction: Design and Computational Modeling of Fabric Soft Pneumatic Actuators for Wearable Assistive Devices

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Correction to: Scientific Reports https://doi.org/10.1038/s41598-020-65003-2, published online 15 June 2020

This Article contains errors in Reference 13 which was incorrectly given as:

Nassour, J. & Hamker, F. Enfolded textile actuator for soft wearable robots. In 2018 7th IEEE International Conference on Biomedical Robotics and Biomechatronics (Biorob) (2020).

The correct reference is listed below as ref 1:

1. Nassour, J. & Hamker, F. Enfolded Textile Actuator for Soft Wearable Robots. In 2019 IEEE International Conference on Cyborg and Bionic Systems (CBS), https://doi.org/10.1109/CBS46900.2019.9114425 (2019).

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