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OPEN A multi-scale flow model for production performance analysis in shale gas reservoirs with fractal geometry

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Shale gas reservoirs can be divided into three regions, including hydraulic fracture regions, stimulating reservoir volume regions (SRV regions), and outer stimulating reservoir volume regions (OSRV regions). Due to the impact of hydraulic fracturing, induced fractures in SRV regions are often irregular. In addition, a precise description of secondary fractures in SRV regions is of critical importance for production analysis and prediction. In this work, the following work is achieved: (1) the complex fracture network in the SRV region is described with fractal theory; (2) a dual inter-porosity flow mechanism with sorption and diffusion behaviors is considered in both SRV and OSRV regions; and (3) both multi-rate and multi-pressure solutions are proposed for history matching based on fractal models and Duhamel convolution theory. Compared with previous numerical and analytic methods, the developed model can provide more accurate dynamic parameter estimates for production analysis in a computationally efficient manner. In this paper, type curves are also established to delineate flow characteristics of the system. It is found that the flow can be classified as six stages, including a bi-linear flow regime, a linear flow regime, a transition flow regime, an inter-porosity flow regime from the matrix to the fractures in the inner region, inter-porosity flow regime from matrix to fractures in the outer region, and a boundary dominant flow regime. The effects of the fracture and matrix properties, fractal parameters, interporosity flow coefficients, and sorption characteristics on type curves and production performance were studied in detail. Finally, production performance was analyzed for Marcellus and Fuling shale gas wells, in the U.S.A. and China, respectively.

The successful exploitation of shale gas heavily depends on the combination of horizontal drilling, completions, and fracturing technology^{1,2}. It has been proven that multi-stage fracturing horizontal wells constitute a very effective way to exploit low-permeability shale gas reservoirs. Due to the complex fracture network created in stimulated reservoir volume regions, it is a great challenge to accurately analyze production performance and evaluate post-fracture performance in such complex fractured reservoirs³.

Since 1972, many analytical and semi-analytical methods on production and flow behaviors in conventional gas and shale gas reservoirs have been utilized to simulate pressure transient behavior for horizontal wells with hydraulic fractures. Soliman et al.⁴ analyzed fluid flow mechanisms for multi-fractured horizontal wells and presented an approximate model to investigate the influence of fracture number, fracture orientation, fracture direction, fracture conductivity, and horizontal well location on flow behaviors. Larsen and Hegre⁵ presented two kinds of models for fractured horizontal wells with multiple fractures with finite conductivity: circular fractures with radial flow and vertical fractures with linear flow. For circular fractures, a cylindrical coordinate system is used with the perpendicular axis of the fracture coinciding with the z axis and the center of the fracture located at z=0. The fracture size is given by the width, the well radius r_w and fracture outer radius r_f . For a vertical fracture, a Cartesian coordinate system is used with the x axis chosen as vertical axis, the y axis coinciding with the axis of the wellbore, and the center of the fracture located at z = 0. The fracture size is given by the width, the fracture half-length x_f away from the wellbore, and the fracture half-length y_f along the wellbore. Guo and Evans⁶ presented a randomly distributed vertical fractures model to predict production performance, and generated type

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Figure 1. Schematic diagram of multiscale mechanism.

curves to estimate reservoir properties and fracture characteristics. Bin *et al.*⁷ presented an improved analytical solution for fractured horizontal wells with different fracture intensities to investigate the effect of fracture properties on flow characteristics. However, due to constant rate assumption, the model cannot be applied to interpret production data. Wang *et al.*⁸ proposed a semi-analytical model in tight oil reservoirs with fractal geometries, which was used to describe complex pore sizes and random fractures in porous media. Since sorption characteristics were not incorporated into their model, the model cannot consider the effect of sorption on production. A technique was introduced by Rbeawi and Tiab⁹ to interpret the pressure transient behavior of fractured horizontal wells. The distribution of hydraulic fractures could be longitudinal or transverse, vertical or inclined, symmetrical or asymmetrical. Brown *et al.*¹⁰ and Stalgorova and Mattar¹¹ proposed a classical tri-linear flow model to simulate production performance of fractured horizontal wells in unconventional reservoirs. However, complex geometries and sorption characteristics were not taken into account in these studies, so that they were not suitable for production performance analysis in shale gas reservoirs.

The above studies⁴⁻¹¹ mainly focused on fluid flow in primary fractures, and ignored fluid flow inside secondary fractures and matrix. Due to the influence of induced fractures, uniform fracture models were not applicable to describe heterogeneous SRV zones. Some scholars attempted to utilize numerical models with a discrete fracture network to describe secondary fractures in SRV zones¹²⁻¹⁵. Although the production performance of a complex fracture network can be discerned through the use of numerical methods, numerical simulation is less attractive and pragmatic due to the large amount of requisite knowledge and time-consumption during the history matching process³. In contrast, the analytical model is an alternative for accurately forecasting flow behaviors and calculation efficiency.

Fractal geometry has shown potential in the analysis of flow and transport properties in porous media. Katz and Thompson¹⁶ were the pioneers to find experimental evidence that indicated that the pore spaces of a set of sandstone samples were fractals and self-similar over three to four orders of magnitude in length. Fractal theory can also describe complex fracture shape in shale gas and is easy to apply to obtain analytical solutions. Chang and Yortsos¹⁷ introduced fractal theory into petroleum engineering, and reported that the permeable fractures embedded within the matrix would be arranged in a fractal dimension. Cossio *et al.*¹⁸ presented a model with fractal geometry to develop a rapid and accurate semi-analytical solution for flow in a single vertical fracture that fully penetrates a homogeneous infinite-acting reservoir. Yao *et al.*¹⁹ proposed a fractal double-porosity model for the transient flow analysis of fluids. Kong *et al.*²⁰ developed the basic formulae of seepage velocity, permeability, and porosity in both porous and fractured fractal media. Wang *et al.*³ presented semi-analytical modelling of flow behavior in fractured media with fractal geometry. Zhang *et al.*²¹ proposed an approach for estimating the size and equivalent permeability of fractal SRV zones for vertically fractured wells in tight reservoirs.

The proposed fluid flow models with fractal geometry^{3,16-21} are convenient for conducting pressure transient analysis for understanding flow in complex reservoirs²²⁻²⁵. Random fractures will be produced during the process of hydraulic fracturing. Fractal theory can exhaustively describe the randomness of pore sizes and gas reservoir heterogeneity²⁴. However, most of the previous models are only involved in the aspects of pressure transient analysis in tight reservoirs, while shale multi-scale flow characteristics are not considered⁴⁻¹². Second, gas PVT is assumed to be constant, so that the final results will lead to an assessment of errors. However, gas PVT changes with pressure in the development of shale gas reservoirs. Third, the characteristics of fractal geometry in SRV regions are not reflected in their models⁴⁻¹².

In this paper, an improved tri-linear flow model in shale gas reservoirs with fractal geometry is presented to analyze and predict production performance of multi-fractured wells. First, multi-scale flow mechanism in shale gas reservoirs was considered in the analytical model (Fig. 1). Second, the main fractures were considered into longitudinal rectangular fractures and secondary fractures in the SRV zone were described using fractal theory. Third, gas PVT changed with reservoir pressure in this paper, and a multi-rate solution with variable pressure was also proposed to interpret real well production data measured under various production systems. Finally, the downhill Simplex method was employed to form the history matching procedure.

Methodology

Conceptual model. Figure 1 presents the conceptual model of stimulated reservoir volume (SRV) with fractal geometry. Many authors have presented analytical models to investigate regular fracture networks, such as the single planar hydraulic fractures network and orthogonal hydraulic fractures network⁴⁻¹⁵.

A schematic diagram of the presented model is shown in Fig. 2. Shale gas flow can be divided into three flow regions: flow in hydraulic fractures defined as region 1 (hydraulic fracture region); flow in the SRV region defined



Figure 2. Schematic of flow: (**a**) flow regions in multi-stage fractured horizontal well; (**b**) flow unit with SRV region and OSRV region.

as region 2 (inner region); and flow in the OSRV region defined as region 3 (outer region). To establish mathematical models, the following basic assumptions are made:

- (1) Darcy flow occurs in hydraulic fractures;
- (2) Random fractures in SRV regions are considered using fractal geometry;
- (3) The OSRV region could be homogenous or double porosity with sorption behaviors;
- (4) Sorption characteristics are considered in the rock matrix;
- (5) The compressibility factor and viscosity change with pressure;
- (6) The Z-factor changes with pressure;
- (7) Knudsen diffusion and slippage effects are considered in the matrix model.

Model establishment. Different from conventional reservoirs, shale gas seepage often exhibits strong nonlinearity⁸. In addition, physical parameters, such as the viscosity, compressibility factor and deviation factor, are functions of pressure. However, these methods are effective for only specific problems. The viscosity, compressibility and deviation factor of shale gas change with pressure, which leads to a non-linear seepage equation. The pseudo-time and pseudo-pressure^{26–28} are defined and a detailed deduction is provided in Appendix A of the Supplementary File. These definitions can be written in the following forms:

Pseudo-pressure:

$$m(p) = \frac{\mu_i Z_i}{p_i} \int_0^p \frac{p}{\mu Z} \, dp \tag{1}$$

Pseudo-time:

$$t_a = \int_0^t \frac{\mu_{gi} c_{ii}}{\mu_g(p) c_i(p)} dp \tag{2}$$

where *p* is pressure, Pa; μ is viscosity, Pa=s; c_{ti} is initial total compressibility, Pa⁻¹; c_t is total compressibility, Pa⁻¹; t is time, s; *Z* is deviation factor; and P_i is initial pressure, Pa.





Matrix model. Matrix inter-porosity flow occurs in both SVR regions and OSRV regions, as shown in Fig. 2. The spherical element was assumed to flow in the matrix, and a comprehensive continuity equation with sorption can be formulated as:

$$-\frac{1}{r_{im}^2}\frac{\partial}{\partial r_{im}}(r_{im}^2\rho_{im}v_{im}) = \frac{\partial(\rho_{im}\phi_{im})}{\partial t_a} + \rho_{sc}\frac{\partial V_i}{\partial t_a}$$
(3)

where V_i is sorption volume, m³/m³; ρ_{im} is gas density in the matrix, kg/m³; ρ_{sc} is standard condition gas density, kg/m³; ν_{im} is velocity in the matrix, m/s; t_a is pseudo-time, s. i = o, i can represent the outer reservoir (region 3) or inner reservoir (region 2), respectively. Pseudo-time t_a is defined in Eq. 2. The total compressibility in shale has been previously presented^{29,30} and can be expressed as:

$$c_t = \left(c_g[S_{gi} - c_{ep}] - \frac{\partial c_{ep}}{\partial p} + c_d\right)$$
(4-1)

$$c_{ep} = (c_f + c_w S_{wi})(p_i - p)$$
(4-2)

$$c_d = \frac{\rho_B B_g V_L}{\phi} \left(\frac{p_L}{(p_L + p)^2} \right)$$
(4-3)

where c_g is gas compressibility, Pa^{-1} ; S_{gi} is gas saturation; c_{ep} is intermediate variables; c_s is sorption compressibility, Pa^{-1} ; c_f is formation compressibility, Pa^{-1} ; c_w is water compressibility, Pa^{-1} ; S_{wi} is initial water saturation; B_g is gas volume coefficient; V_L is Langmuir volume, m^3/kg ; p_L is Langmuir pressure, Pa; ρ_B is density of shale, kg/m^3 ; and φ is porosity. Accounting for gas slippage and gas diffusion, gas velocity in the matrix can be expressed as:

$$v_{im} = -k_{im}F_{iD}\frac{\partial p_{im}}{\partial r_{im}} = -k_{im}[(1+8\alpha k_n) + \mu_g D_g c_g/k_{im}]\frac{\partial p_{im}}{\partial r_{im}}$$
(5)

The equation of gas state is given as:

$$\rho_{im} = \frac{p_{im}M}{nZRT} \tag{6}$$

Substituting Eq. 1, and Eqs 4 through 6 into Eq. 3 produces the governing equation of matrix:

$$\frac{1}{r_{im}^2} \frac{\partial}{\partial r_{im}} \left(r_{im}^2 k_{im} \left[(1 + 8\alpha kn) + \frac{\mu_g D_g c_g}{kim} \right] \frac{\partial m_{im}}{\partial r_{im}} \right] = \phi_{im} c_{imt} \frac{\partial m_{im}}{\partial t_a}$$
(7)

and

Parameter name	Values	Units	Definitions
Pi	3924	psia	Initial pressure
Т	220	°F	Reservoir temperature
x _f	171	ft	Fracture half-length
L	4175	ft	Horizontal well length
C _{fD}	30	1	Fracture conductivity
n _f	15	1	Fracture number
k _{If}	1.0000E-03	md	Initial permeability of inner region
k _{Of}	6.0000E-04	md	Permeability of outer region
h	150	ft	Formation thickness
φ _t	7.1	%	Porosity
Sg	66	%	Gas saturation
So	0	%	Oil saturation
S _w	34	%	Water saturation
C _f	5.60E-06	1/psi	Pore compressibility factor
d	2	1	Fractal dimension
θ	0	1	Connectivity index
Ct	2.01E-04	1/psi	Total compressibility factor
x _e	4175	ft	Reservoir length
y _e	700	ft	Reservoir width
r _w	0.35	ft	Well radius
S _C	0.0434	1	Choking skin
VL	200	scf/ton	Langmuir volume
P _L	1200	psia	Langmuir pressure
ρ_{B}	2.6	g/cm ³	Shale rock density

Table 1. Data for model validation.

$$c_{imt} = c_g + c_{im} + c_{id} \tag{8}$$

where $c_{\rm im}$ is matrix compressibility, Pa⁻¹. The initial condition and boundary conditions can be given as:

r

$$n_{im}|_{t_a=0} = m_i(p_i) \tag{9-1}$$

and

$$m_{im}|_{r_{im}=R} = m_{if} \tag{9-2}$$

$$\frac{\partial m_{im}}{\partial r_{im}}\Big|_{r_{im}=0} = 0 \tag{9-3}$$

Equation 7 through 9 constitute the matrix seepage governing equation in both the SRV and OSRV regions. The dimensionless equations and solution method are provided in Appendix B.

Natural fracture model of the OSRV region (region 3). According to the above definitions of pseudo-pressure and pseudo-time, assuming one-dimensional flow in the *x* direction, as shown in Fig. 3, the diffusivity equation and the associated boundary conditions for the outer reservoir are given by:

$$\frac{\partial^2 m_{of}(p)}{\partial x^2} = \frac{\phi_{of} c_{oft} \mu_{gi}}{k_{of}} \frac{\partial m_{of}(p)}{\partial t_a} + \frac{3}{R} \frac{k_{om} F_{oD}}{k_{of}} \frac{\partial m_{om}(p)}{\partial r_{om}} \bigg|_{r_{om}=R}$$
(10)

$$\left(\frac{\partial m_{of}(p)}{\partial x}\right)_{x=x_e} = 0 \tag{11}$$

$$m_{of}(p)_{x=x_f} = m_{If}(p)_{x=x_f}$$
 (12)

where k_{of} is the fracture permeability in the outer region, m^2 ; φ_{of} is fracture porosity in the outer region; k_{om} is matrix permeability in the outer region, m^2 ; x_f is fracture half-length, m; x_e is boundary length, m; c_{off} is total compressibility in the outer region, Pa⁻¹; and m_{of} is fracture pseudo-pressure in the outer region, Pa. Eqs 10 through 12 constitute the natural fracture model of the OSRV region.



Figure 4. Validation of rate solution at constant pressure conditions for a special case ($d = 2, \theta = 0, f(s) = 1$, g(s) = 1).

Natural fracture model of the SRV region (region 2). The change in porosity and permeability in the inner region are large and heterogeneous. Therefore, the fractal model can be utilized to describe SRV behavior. Furthermore, we work exclusively in Cartesian coordinates. Thus, the fractal relationships are given as^{17,18}:

$$k_{\rm lf}^{\rm Fractal}(y) = k_{\rm lf} \left(\frac{y}{x_f}\right)^{d-\theta-2} = k_{\rm lf} y_D^{d-\theta-2}$$
(13-1)

$$\phi_{If}^{Fractal}(y) = \phi_{If} \left(\frac{y}{x_f}\right)^{d-2} = \phi_{If} y_D^{d-2}$$
(13-2)

Assuming one-dimensional flow in the *y* direction, the diffusivity equation is given by:

$$\frac{\partial}{\partial y} \left(k_{lf}^{Fractal} \frac{\partial m_{lf}(p)}{\partial y} \right) + \left(\frac{y}{x_f} \right)^{d-2} \frac{k_{lf}}{x_f} \left(\frac{\partial m_{lf}(p)}{\partial x}_{x=x_f} \right) = \left(\frac{y}{x_f} \right)^{d-2} \phi_{lf} c_{lft} \mu \frac{\partial m_{lf}(p)}{\partial t_a} + \left(\frac{y}{x_f} \right)^{d-2} \frac{3}{R} \frac{k_{lm} F_{ID}}{1} \frac{\partial m_{Im}(p)}{\partial r_{lm}} \Big|_{r_{lm}=R}$$
(14)

Substituting Eq. 13 into Eq. 14 yields:

$$\left(\frac{y}{x_{f}}\right)^{d-\theta-2} k_{If} \left[\frac{\partial^{2} m_{If}}{\partial y^{2}} + \frac{d-\theta-2}{y} \frac{\partial m_{If}}{\partial y}\right] + \left(\frac{y}{x_{f}}\right)^{d-2} \frac{k_{If}}{x_{f}} \left(\frac{\partial m_{If}(p)}{\partial x}_{x=x_{f}}\right) \\
= \left(\frac{y}{x_{f}}\right)^{d-2} \phi_{If} c_{Ift} \mu \frac{\partial m_{If}(p)}{\partial t} + \left(\frac{y}{x_{f}}\right)^{d-2} \frac{3}{R} \frac{k_{Im} F_{ID}}{1} \frac{\partial m_{Im}(p)}{\partial r_{Im}} \Big|_{r_{Im}=R}$$
(15)

The boundary conditions for the inner reservoir are given by:

$$\left(\frac{\partial m_{lf}}{\partial y}\right)_{y=y_e} = 0 \tag{16-1}$$

and

$$m_{If}\Big|_{y=\frac{\omega}{2}} = m_F|_{y=\frac{\omega}{2}}$$
 (16-2)

where $k_{\rm if}$ is the fracture permeability in the inner region, m²; $\varphi_{\rm if}$ is fracture porosity in the inner region; $k_{\rm im}$ is matrix permeability in the inner region, m²; $x_{\rm f}$ is fracture half-length, m; $c_{\rm if}$ is fracture compressibility in the inner region, Pa⁻¹; $c_{\rm ift}$ is total compressibility of the inner region, Pa⁻¹; $m_{\rm if}$ is fracture pseudo-pressure of the inner region, Pa; d is fractal dimension representing the dimension of fractal fracture network embedded in the Euclidean matrix; and θ is connectivity index characterizing the diffusion process.

Eqs 15 and 16 are the natural fracture model of the OSRV region, and the solution method is presented in Appendix B.

Parameter name	Values	Units	Definitions
nf	1	Dimensionless	Fracture number
x _{eD}	24	Dimensionless	Reservoir length
y _{eD}	6	Dimensionless	Reservoir width
C _{fD}	20	Dimensionless	Fracture conductivity
C _{RD}	2	Dimensionless	Region conductivity
λ_{I}	0.03	Dimensionless	Inter-porosity flow coefficient of inner region
λο	3	Dimensionless	Inter-porosity flow coefficient of outer region
$\omega_{\rm I}$	0.00001	Dimensionless	Permeability of outer region
ω	0.000001	Dimensionless	Formation thickness
d	2.005	Dimensionless	Fractal dimension
θ	0	Dimensionless	Connectivity index

Table 2. Dimensionless data for flow characteristics analysis.



Figure 5. Validation of pressure solution at variable rate conditions for a special case ($d = 2, \theta = 0, f(s) = 1$, g(s) = 1).

Hydraulic fracture model (region 1). The flow in hydraulic fractures can be expressed as:

$$\frac{\partial \left(k_F \frac{\partial m_F(p)}{\partial x}\right)}{\partial x} + \frac{2k_{If}}{\omega} \frac{\partial m_{If}(p)}{\partial y}\bigg|_{y=\frac{\omega}{2}} = \phi_F c_F \mu_{gi} \frac{\partial m_F(p)}{\partial t_a}$$
(17)

Inner boundary condition can be given as:

0 ())

$$\left. \frac{\partial m_F}{\partial x} \right|_{x=0} = \frac{Q\mu_{gi}}{2whk_F} \tag{18-1}$$

Outer boundary condition can be expressed as:

$$\left. \frac{\partial m_F}{\partial x} \right|_{x=x_f} = 0 \tag{18-2}$$

where Q is flow rate, m³/s; c_F is fracture compressibility, Pa⁻¹; w is fracture width, m; φ_F is hydraulic fracture porosity; and k_F is the fracture permeability, m².

Solution of Mathematical Model

Bottom-hole pressure solution at constant rate conditions. A constant-rate solution can be obtained by using the Laplace transform method (Appendix B of the supplementary file), and we provide the solution of the non-linear difference equation using pseudo-pressure and pseudo-time definitions. The dimensionless definitions of the model and dimensionless solution at a constant rate condition are given as:

$$\overline{m}_{FD}(p) = \frac{\pi}{C_{FD}s_{\sqrt{\alpha_F}}} \frac{\cosh[\sqrt{\alpha_F}(1-x_D)]}{\sinh(\sqrt{\alpha_F})}$$
(19)



Figure 6. Flow characteristics of pressure and pressure derivative curves.

where

$$\alpha_F = 2\beta_F / C_{FD} + s / \eta_{FD} \tag{20}$$

$$\beta_{F} = -\left(\frac{w_{D}}{2}\right)^{\gamma-1} \sqrt{\alpha_{o}} \frac{K_{n-1}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} y_{eD}^{\gamma}\right] I_{n-1}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} \left(\frac{w_{D}}{2}\right)^{\gamma}\right] - I_{n-1}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} y_{eD}^{\gamma}\right] K_{n-1}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} \left(\frac{w_{D}}{2}\right)^{\gamma}\right]}{I_{n}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} \left(\frac{w_{D}}{2}\right)^{\gamma}\right] K_{n-1}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} y_{eD}^{\gamma}\right] + I_{n-1}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} y_{eD}^{\gamma}\right] K_{n}\left[\frac{\sqrt{\alpha_{o}}}{\gamma} \left(\frac{w_{D}}{2}\right)^{\gamma}\right]}$$
(21)

$$\alpha_o = \frac{\beta_o}{C_{RD} \gamma_{eD}} + u_I \tag{22}$$

$$\beta_o = \sqrt{u_o} \tanh[\sqrt{u_o}(x_{eD} - 1)]$$
(23)

$$u_I = s[f(s)] = s \left[\frac{\omega_I}{\eta_{ID}} + \frac{\lambda_I \eta_{ID}}{5s} (\tau_I \coth \tau_I - 1) \right]$$
(24)

$$u_o = s[g(s)] = s \left[\frac{\omega_o}{\eta_{oD}} + \frac{\lambda_o \eta_{oD}}{5s} (\tau_o \coth \tau_o - 1) \right]$$
(25)

In the above results, one-dimensional linear flow in the hydraulic fracture is considered. Flow choking within the fracture must be considered by using the following equation that was presented by Mukherjee and Economides³¹:

$$\overline{m}_{FD}(p) = \frac{\pi}{C_{FD}s_{\sqrt{\alpha_F}}} \frac{\cosh[\sqrt{\alpha_F}(1-x_D)]}{\sinh(\sqrt{\alpha_F})} + \frac{S_C}{s}$$
(26)

S_C is flow skin, and expressed as:

$$S_C = \frac{k_{IJ}h}{k_F w_F} \left[\ln \left(\frac{h}{2r_w} \right) - \frac{\pi}{2} \right]$$
(27)

Bottom-hole rate solution at constant pressure conditions. Note that the constant-pressure solution and constant-rate solution conform to the relation suggested by Van-Everdingen and Hurst³²:

$$\overline{m}_{FD} \times \overline{q}_{FD} = \frac{1}{s^2}$$
(28)

Therefore, the rate solution at a constant pressure condition can be obtained as:

$$\overline{q}_{FD} = \frac{C_{FD}\sqrt{\alpha_F}}{s\pi} \frac{\sinh(\sqrt{\alpha_F})}{\cosh[\sqrt{\alpha_F}(1-x_D)]}$$
(29)



Figure 7. Influence of sensitive factors on flow characteristics: (a) fractal dimension; (b) connectivity index θ ; (c) inter-porosity flow coefficient of inner region λ_{I} ; (d) inter-porosity flow coefficient of inner region λ_{o} ; (e) storage coefficient of inner region ω_{o} ; (g) fracture conductivity C_{fD} ; (h) fracture half-length x_{f} .

The solutions at variable rate or variable pressure conditions. During the process of production, both the rate and pressure change with the time. Constant rate and constant pressure solutions cannot be applied to a real reservoir. Through using convolution theory^{29,33}, the variable rate and variable pressure solutions can be given by

$$\mathbf{m}_{wD}(t_{Dn}) = \sum_{i=1}^{n-1} \frac{q(t_i)}{q(t_n)} [\mathbf{m}_{FD}(t_{Dn} - t_{Di-1}) - \mathbf{m}_{FD}(t_{Dn} - t_{Di})] + \mathbf{m}_{FD}(t_{Dn} - t_{Dn-1})$$
(30)



Figure 8. Influence of sensitive factors on production rate and cumulative production: (**a**) fractal dimension; (**b**) connectivity index θ ; (**c**) Langmuir volume V_L ; (**d**) Langmuir pressure p_L ; (**e**) fracture half-length x_{ji} (**f**) fracture conductivity C_{jD} ; (**g**) inter-porosity flow coefficient; (**h**) storage coefficient.

$$q_{wD}(t_{Dn}) = \sum_{\substack{i=1\\n>1}}^{n-1} m_{FDi} [q_{FD}(t_{Dn} - t_{Di-1}) - q_{FD}(t_{Dn} - t_{Di})] + q_{FD}(t_{Dn} - t_{Dn-1})$$
(31)

Calculation process. The material balance equation must be established to calculate pseudo-time and pseudo-pressure. The modified gas compressibility factor and material balance equation that were proposed by Moghadam³⁰ for shale gas reservoirs were adopted in this paper.

The modified gas compressibility factor Z** is defined as:

 Z^{*}

$$^{**} = \frac{p}{\left[\frac{1}{S_{gi}}\frac{p}{Z}(S_{gi} - c_{ep} - c_{d}) + \frac{p_{i}}{Z_{i}}\left(\frac{G}{G_{f}} - 1\right)\right]^{G_{f}}_{G}}$$
(32)

Parameter name	Values	Units	Definitions
p _i	3924	psia	Initial pressure
Т	220	°F	Reservoir temperature
x _f	171	ft	Fracture half-length
L	4175	ft	Horizontal well length
C _{fD}	30	1	Fracture conductivity
n _f	15	1	Fracture number
k _{If}	1.0000E-03	md	Initial permeability of inner region
k _{Of}	6.0000E-04	md	Permeability of outer region
h	150	ft	Formation thickness
φ _t	7.1	%	Porosity
Sg	66	%	Gas saturation
So	0	%	Oil saturation
Sw	34	%	Water saturation
C _f	5.60E-06	1/psi	Pore compressibility factor
d	2.01	1	Fractal dimension
θ	0	1	Connectivity index
λ_{I}	1	1	Inter-porosity of inner region
λο	1	1	Inter-porosity of outer region
ωI	0.7	1	Storage coefficient of inner region
ω	0.7	1	Storage coefficient of outer region
Ct	2.01E-04	1/psi	Total compressibility factor
x _e	4175	ft	Reservoir length
y _e	700	ft	Reservoir width
r _w	0.35	ft	Well radius
S _C	0.0434	1	Choking skin
VL	200	Scf/ton	Langmuir volume
PL	1200	psia	Langmuir pressure
ρ _B	2.6	g/cm ³	Shale rock density

Table 3. Data for sensitive parameters analysis.

where the parameters c_{ep} and c_d are defined in Eq. 4. The modified material balance equation can be written as:

$$\frac{p}{Z^{**}} = \frac{p_i}{Z_i^{**}} \left(1 - \frac{G_p}{G} \right)$$
(33)

The average pressure can be determined by taking advantage of Eqs 32 and 33, and pseudo-pressure and pseudo-time can be calculated. The entire calculation process is illustrated in Fig. 3, which shows the procedures of variable rate solution and variable pressure solution. The procedures above could be applied to interpret production data from shale gas reservoirs.

Validation of solution. The accuracy of the coupled model was validated by comparing our results with those of an analytical solution using IHS Harmony software. The settings of the reservoir and fracture properties are listed in Table 1. We selected special cases of fractal parameters d = 2 and $\theta = 0$, which represents constant permeability and constant porosity, as the fractal geometry has been not considered in commercial software. The total analysis time is 255 d. Figures 4 and 5 present the validation results by comparing the analytical results based on the proposed fractal model with the analytical solution from commercial software¹⁰. The algorithm from IHS Harmony software was presented by Brown *et al.*¹⁰ in 2009. A validation of the rate solution under a constant pressure condition of 2,000 psi is shown in Fig. 4. It is apparent that the production rate and cumulative gas production obtained from the proposed model agree very well with those from the analytical solution. A validation of the pressure solution under a variable rate condition is shown in Fig. 5. Figure 5 presents five cycles of open and shut well conditions. The pressure solution associated with a variable rate and the rate solution associated with variable pressure can be calculated using Eqs 30 and 31, respectively. The same parameters are listed in Table 1, and the production rate value for open well is set to 2 MMscf. Fractal parameters remain as d = 2 and $\theta = 0$. The solution of the pressure under variable rate conditions is consistent with the solution from the commercial software IHS Harmony.

Results and Discussion

Flow characteristics analysis of type curves. Flow characteristics analysis of pressure and pressure derivative curves is shown in Fig. 6 and the basic data used are shown in Table 2. It is apparent that the fluid flow in shale gas reservoirs can be classified into six stages:



Figure 9. Field example from Marcellus shale gas wells in the U.S.A.: (**a**) real rate and pressure data; (**b**) history matching of production data; (**c**) forecast production performance.

- The bi-linear flow regime is a straight line with a slope of 1/4 on the pressure derivative curve. The flow of gas occurs simultaneously both within hydraulic fractures and near them.
- (2) The linear flow regime is a straight line with a slope of 1/2 on the pressure derivative curve. In this period, linear flow around the fractures occupies the dominant position.
- (3) The transition flow regime (a) shows an indefinite slope line on the pressure derivative curve.
- (4) The first inter-porosity flow regime is a regime of supplementation from the shale matrix to the fracture system in the inner region. The derivative curve exhibits the first V-shaped segment.
- (5) The second inter-porosity flow regime represents the inter-porosity flow from the matrix system to the fracture system in the outer region. The pressure derivative curve shows the second V-shaped segment.
- (6) The boundary dominant flow regime is a straight line with a slope of 1 on the pressure derivative curve. In this regime, the process of inter-porosity flow is terminated, and the pressure between the matrix and fractures have increased to a state of dynamic balance.

Effect of sensitive factors on flow characteristics. Figure 7 shows the influence of parameters, including the fractal dimension *d*; connectivity index θ ; transfer coefficients of the inner region and outer region, λ_I and λ_O , respectively; storage coefficients of the inner region and outer region, ω_I and ω_O , respectively; and conductivity of fracture and region on pressure and pressure derivative curves. The same data are also listed in Table 2.

Influence of fractal geometry parameters on type curves. Figure 7a presents the effect of fractal dimension *d* on plots of type curves, wherein fractal dimension d values are set to 1.6, 2, and 2.4. A larger *d* represents a more complex structure of fractal natural fractures. It is concluded that the fractal dimension *d* has a

Parameter name	Values	Units	Definitions
p _i	3924	psia	Initial pressure
Т	220	°F	Reservoir temperature
x _f	120	ft	Fracture half-length
L	4175	ft	Horizontal well length
C _{fD}	30	1	Fracture conductivity
n _f	12	1	Fracture number
k _{If}	1.0000E-03	md	Initial permeability of inner region
k _{of}	1.0000E-05	md	Permeability of outer region
h	150	ft	Formation thickness
φ _t	7.1	%	Porosity
Sg	66	%	Gas saturation
So	0	%	Oil saturation
S _w	34	%	Water saturation
C _f	5.60E-06	1/psi	Pore compressibility factor
d	2	1	Fractal dimension
θ	0	1	Connectivity index
λ_{I}	1	1	Inter-porosity of inner region
λο	1	1	Inter-porosity of outer region
ωΙ	0.7	1	Storage coefficient of inner region
ω	0.7	1	Storage coefficient of outer region
Ct	2.01E-04	1/psi	Total compressibility factor
x _e	4175	ft	Reservoir length
y _e	700	ft	Reservoir width
r _w	0.35	ft	Well radius
S _C	0	1	Skin
VL	200	scf/ton	Langmuir volume
P _L	1200	psia	Langmuir pressure
ρΒ	2.6	g/cm3	Shale rock density

Table 4. Basic data for Marcellus shale gas wells.

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significant impact on flow characteristics within all periods. Dimensionless pressure p_D reflects pressure depletion during the production periods. From the pressure curve in Fig. 7a, it is indicated that a large fractal dimension will result in a small pressure depletion, which implies that the production rate will be enhanced under the same pressure drop. In addition, fracture morphology becomes more complex when fractal dimension *d* becomes large. Figure 7b presents the effect of the connectivity index of natural fractures in SRV region θ on plots of type curves. The θ values are set to 0, 0.4, and 0.8. Different from the fractal dimension, a large connectivity index will result in a large pressure depletion, which indicates that the production rate will be reduced under the same pressure drop. Moreover, a larger θ value leads to worse connectivity in the formation. In other words, pressure depletion is proportional to the connectivity index of natural fractures in the SRV region and is inversely proportional to fractal dimension.

Influence of matrix transfer and storage parameters on type curves. Figure 7c through d show the effect of the inter-porosity coefficient between the matrix and natural fractures on type curves. It reflects gas flow ability from the matrix to natural fractures in the inner region. Similarly, the inter-porosity flow coefficient of outer region λ_0 is proportional to matrix permeability k_{om} of the outer region, and is inversely proportional to fracture permeability k_{of} of the outer region. Thus, it reflects the gas flow ability from the matrix to natural fractures in the outer region.

The mechanism of the theory reveals that a large inter-porosity flow coefficient reflects relatively strong matrix flow ability and weak fracture flow ability. Figure 7d presents the effect of the inter-porosity flow coefficient λ_o on type curves. The values are set to 0.03, 0.3, and 3. It is seen from Fig. 8d that a large λ_o value corresponding to strong matrix flow ability will lead to a small pressure depletion as the matrix compensates for pressure loss by supplying natural fractures. From the derivative curves of Fig. 7c and d, it is observed that flow in intermediate time is mainly affected by the inter-porosity flow coefficient.

Figure 7e and f show the effect of the storage coefficient of natural fractures on the type curves. The ω_I values reflect natural fracture energy, which was set to 0.000001, 0.1, and 0.5 in the inner region. The ω_I values reflect natural fracture energy and are set to 0.000001, 0.00001, and 0.0001 in the inner region. It is known from the pressure curves of both figures that a large storage coefficient will lead to a small pressure depletion due to the storage of rich gas resources in the natural fractures. This results in an extension of the linear flow duration, which is indicated from the derivative curves of both figures. From the derivative curves of Fig. 7e and f, it could also be concluded that flow in early and medium time is mainly influenced by the storage coefficient.



Figure 10. Field example from Fuling shale gas wells in China: (**a**) real rate and pressure data; (**b**) history matching of production data; (**c**) forecast production performance.

Influence of fracture conductivity and region conductivity on type curves. Figure 7g shows the effect of the hydraulic fracture conductivity on the type curves. The C_{fD} values reflect the flow ability of shale gas in hydraulic fractures and are set to 1, 5, and 20. It is observed from the pressure curves that a small fracture conductivity will lead to a large pressure depletion, which implies that the production rate will be enhanced by improving fracture conductivity. However, the production rate is improved only at an early time. It is apparent from the pressure derivative curves that there is no effect on flow in middle and late time.

Figure 7h presents the effect of the inner region conductivity C_{RD} on type curves. The C_{RD} values indicate flow ability of shale gas in the inner region and are set to 1, 2, and 5. C_{RD} has an important impact on fluid flow during all production periods. According to the definition of Eq. B-29, C_{RD} is proportional to the fracture permeability of the inner region and is inversely proportional to the fracture permeability of the outer region. The pressure curves in Fig. 7h show that a large region conductivity will lead to a large pressure depletion. It is apparent from the derivative curves that the shapes of the curves do not change as the inner region conductivity changes in the bi-linear flow period.

Effect of sensitive factors on production performance. Figure 8 shows the effects of different parameters, including fractal dimension *d*, connectivity index θ , Langmuir volume V_I , Langmuir pressure P_I , fracture half-length x_{fi} fracture conductivity C_{fD} , inter-porosity flow coefficient of inner region and outer region λ_I and λ_O , respectively, and storage coefficients of the inner region and outer region ω_I and ω_O , respectively, on production rate and cumulative production. The data used are listed in Table 3. The bottom-hole pressure was set to 2,000 psi in all cases.

Parameter name	Values	Units	Definitions
p _i	11521.7	psia	Initial pressure
Т	219.2	°F	Reservoir temperature
x _f	120	ft	Fracture half-length
L	4926.56	ft	Horizontal well length
C _{fD}	30	1	Fracture conductivity
n _f	21	1	Fracture number
k _{If}	1.0000E-03	md	Initial permeability of inner region
k _{Of}	1.0000E-05	md	Permeability of outer region
h	136.12	ft	Formation thickness
φ _t	3.71	%	Porosity
Sg	80	%	Gas saturation
So	0	%	Oil saturation
S _w	20	%	Water saturation
C _f	3.45E-07	1/psi	Pore compressibility factor
d	2	1	Fractal dimension
θ	0	1	Connectivity index
λ_{I}	1	1	Inter-porosity of inner region
λο	1	1	Inter-porosity of outer region
ωI	0.7	1	Storage coefficient of inner region
ω	0.7	1	Storage coefficient of outer region
Ct	5.01E-04	1/psi	Total compressibility factor
x _e	4926.56	ft	Reservoir length
y _e	1968	ft	Reservoir width
r _w	0.164	ft	Well radius
S _C	0	1	Skin
VL	80.7754	scf/ton	Langmuir volume
P _L	869.565	psia	Langmuir pressure
ρΒ	2.6	g/cm3	Shale rock density

Table 5. Basic data for Fuling shale gas wells.

Fractal geometry. The fractal dimension values are set to 1.99, 2, and 2.01. Figure 8a presents the effect of fractal dimension *d* on plots of production rate and cumulative production versus time. A larger d represents a more complex structure of the fractal natural fractures. It is observed that the fractal dimension *d* has a significant impact on the solutions throughout the entire production period. A larger *d* value leads to a high production rate and a high cumulative production. In addition, as time increases, the rate first declines rapidly and then declines gradually.

Figure 8b presents the effect of the connectivity index of natural fractures in the SRV region θ on plots of production rate and cumulative production versus time. The θ values were set to 0, 0.01, and 0.2. The connectivity index reflects connectivity and tortuosity between natural fractures. It is apparent from Fig. 8b that the connectivity index of natural fractures in the SRV region has a significant impact on the solutions throughout the entire production period. As shown in Fig. 8b, a larger θ value leads to a low production rate and low cumulative production. This point implies that a larger θ reflects more complicated tortuosity, which will lead to worse connectivity in the formation.

Sorption. Figure 8c presents the effect of the Langmuir volume on production behavior. The Langmuir volume V_L values are set to 100 scf/ton, 200 scf/ton, and 300 scf/ton. It is apparent from the figure that a larger V_L value will result in a high production rate and cumulative production. However, the increase in cumulative production is not obvious. The cumulative productions associated with $V_L = 100$ scf/ton, 200 scf/ton, and 300 scf/ton are $G_p = 622.35$ MMscf, 653.76 MMscf, and 682.26 MMscf, respectively. The fact that shale gas adsorption volume is directly proportional to the Langmuir volume will cause the shale gas adsorption volume to decrease as the Langmuir volume increases.

Figure 8d presents the effect of the Langmuir pressure p_L on plots of production rate and cumulative production versus time. The p_L values are set to 100 psi, 500 psi, and1200 psi. Simulation results show that production rate and cumulative production will increase as the Langmuir pressure increases. The fact that shale gas adsorption volume is inversely proportional to the Langmuir pressure will cause an increasing shale gas adsorption volume as the Langmuir pressure increases.

Fracture parameters. Figure 8e shows the effect of fracture half-length on production behavior. The fracture half-length x_f was set to 141 ft, 171 ft, and 201 ft. It is apparent that a large x_f will lead to a high production rate and cumulative production. A larger x_f value has an important impact on enhancing production rate and

cumulative production. The cumulative production of x_f = 141 ft, 171 ft, and 201 ft are G_p = 570.35 MMscf, 653.76 MMscf, and 734.77 MMscf.

Fracture conductivity also has an important impact on enhancing production rate and cumulative production. Figure 8f presents the effect of fracture conductivity on production behavior. The fracture conductivity C_{fD} values were set to 0.1, 1, and 10. It is apparent that a large C_{fD} value will lead to a high production rate and cumulative production. The cumulative production of $C_{fD} = 0.1$, 1, and 10 are $G_p = 88.48$ MMscf, 272.70 MMscf, and 583.31 MMscf, respectively. In the early stage, effectively increasing fracture conductivity effectively can remarkably improve the production rate and cumulative production.

Matrix transfer and storage coefficients. Figure 8g presents the effect of the inter-porosity flow coefficient of the inner region on production behavior. The fracture inter-porosity flow coefficient λ_I values are set to 0.1, 1, and 10. It is apparent from the figure that a large λ_I value will lead to a high production rate and cumulative production. Figure 8h presents the effect of the storage coefficient of the inner region on production behavior. The fracture storage coefficient ω_I values are set to 0.4, 0.7, and 1. It is apparent from the figure that a large ω_I value will lead to a high production rate and cumulative production rate and cumulative production.

History Matching of Production Data

Automatic history matching. Automatic parameter estimation (APE) is a mathematical process, known as multi-variable optimization, which automatically adjusts a specified set of function parameters to minimize error between the function and measured data. Minimizing the mathematical function is called the objective function. With analytical modelling, the objective function is calculated as follows.

If the Calculate Pressure mode is used:

$$E_{\text{avg}} = \frac{\sum_{i} \left(\frac{|(p_{calc})_i - (p_{hist})_i|}{(p_{hist})_i} \right)}{n_{hist}}$$
(34)

If the Calculate Rate mode is used:

$$E_{\text{avg}} = \frac{\sum_{i} \left(\frac{|(\mathbf{q}_{calk})_{i} - (\mathbf{q}_{hist})_{i}|}{(\mathbf{q}_{hist})_{i}} \right)}{n_{hist}}$$
(35)

where p_{calc} is calculated pressure for the *i*-th point; p_{hist} is historical pressure for the *i*-th point; q_{calc} is calculated rate for the *i*-th point; q_{hist} is historical rate for the *i*-th point; n_{hist} is historical point number; and E_{avg} reflects the difference between the calculated and historical data. Therefore, a smaller E_{avg} indicates a better history match.

The Simplex routine³⁴ is a non-linear regression algorithm used for APE for reservoir and well parameters (k_{lj} , $k_{\rho} G_{D}$, S_{C} , etc.) when modelling pressure and rate transient data. It requires only function evaluations of the objective function, and not the derivatives. Modification of the downhill Simplex method to achieve greater convergence is accomplished by imposing constraints on the parameters during the search. Estimates of the parameters are always checked against preset maximum and minimum values for each parameter. Once the routine has converged on some parameters, it is restarted with a slight perturbation away from the final values and is allowed to converge again. This ensures that the parameter estimates found are not the result of some local minimum in the residual, but rather a more global minimum.

Field examples. *Case 1: Marcellus shale, U.S.A.* Using our model, history matching of production data was performed based on field data. The well is a multi-stage fractured horizontal well with 12 fractures in a typical shale gas reservoir in the Marcellus shale gas field, U.S.A. The pressure data and rate data were acquired from production tests after almost one-year of production. Figure 9a shows the pressure data and rate data from Nov. 24th 2009 to Aug 6th, 2010. The basic input parameters are summarized in Table 4. We selected the fracture permeability of the inner region, the fracture permeability of the outer region, choking skin, fracture half-length, fracture conductivity, fractal dimension, inter-porosity flow coefficient of inner region, and storage coefficient of inner region as uncertain parameters of history matching, which are listed in Table 4 and marked in bold.

Figure 9b presents the historical matching results of production data from Marcellus shale gas wells using our proposed model. Our model fits the pressure and production rate very well. The presented model can also be applied to production performance analysis in complex conditions. Table 4 gives the initial estimation of uncertain parameters in shale gas, and the final matching results are shown in Fig. 9b. The k_{if} value is 0.000463 mD, the S_C value is 0.089, the x_f value is 279.086 ft, the C_{fD} value is 15.1856, the d value is 1.96849, the λ_I value is 1.85974, and the ω_I is 0.128578. The relative error of our model for all of the data is $E_{avg} = 13.58\%$.

 E_{avg} = 13.58%. With the reservoir and fracture parameters determined by history matching, the production performance of the well can be predicted. In this case, the BHP was set to 631 psi from the final production data point. Figure 9c presents the predicted gas production and cumulative production. The cumulative production of the shale gas multi-fractured well with fractal geometry is estimated to be 1381.87 MMscf and the rate of well will become 0.01219 MMscf/d after 20 years. In the first five years, the rate of the well decreases rapidly, and cumulative production of the well increases dramatically. However, in the next 15 years, the rate of the well gradually decreased, and the cumulative production of the well increased slowly. From the fifth year to the twentieth year, the rate of well decreases only from 0.081876 MMscf/d to 0.01219 MMscf/d and cumulative production of well increases only from 1241.7 MMscf to 1381.87 MMscf, which does not constitute a remarkable improvement. In other words, it is not economically feasible to continue developing this shale gas well for up to 20 years.

Case 2: Fuling shale, China. The second well is also a multi-stage fractured horizontal well with 21 fractures in a typical shale gas reservoir in the Fuling high pressure shale gas field, China. The pressure and production rate data were acquired from production test performed over 474 d. Figure 10a presents the pressure and production rate profile from Jan. 7th 2016 to Apr. 24th, 2017. The basic input parameters are summarized in Table 5. The uncertain parameters of history matching are shown in Table 5 and are marked in bold.

As shown in Fig. 10b, our model matched the BHP pressure and production rate very well from the Fuling shale gas field. Table 5 provides an initial estimation of uncertain parameters in the Fuling shale gas field, and the final matching results are shown in Fig. 10b. The k_{If} value is 0.00273 mD, the k_{Of} value is 2.77e-5 mD, the S_C value is 0.107, the x_f value is 127.232 ft, the C_{fD} value is 12.6512, the d value is 2.01746, the λ_I value is 0.28484, and the ω_I is 0.0287237. The relative error of our model for all of the data is $E_{avg} = 4.16\%$.

According to the results, the production performance from Fuling shale gas wells can be predicted. In this case, if the BHP is set at 6948.28 psi, Fig. 10c shows the predicted gas production and cumulative production. The cumulative production of the shale gas multi-fractured well with fractal geometry is estimated to be 1001.43 MMscf after 20 years. In the first four years, the rate of the well decreases rapidly. However, in the next 16 years, the rate of well becomes approximately stable.

Conclusions

In this study, a multi-scale flow model in shale gas reservoirs with fractal geometry was presented to investigate pressure transient response and analyze production performance, through which we examined the effects of shale rock properties and fractal characteristics. From the above analysis, the following conclusions are made:

- (1) The flow characteristics of type curves can be divided into six regimes: bi-linear flow regime, linear flow regime, transition flow regime, inter-porosity flow regime from the matrix to fractures in the inner region, inter-porosity flow regime from matrix to fractures in the outer region, and boundary dominant flow regime, respectively.
- (2) A large fractal dimension represents a complex structure of fractal natural fractures and leads to a small pressure depletion. A large connectivity index, which reflects connectivity and tortuosity among natural fractures, results in a large pressure depletion.
- (3) A large inter-porosity flow coefficient of the outer region and inner region corresponding to strong matrix flow ability will lead to a small pressure depletion because the matrix compensates for pressure loss by supplying natural fractures. A large storage coefficient results in a small pressure depletion due to rich gas resources that are stored by natural fractures.
- (4) A small fracture conductivity and a large region conductivity leads to a large pressure depletion.
- (5) A large fractal dimension, small connectivity index, large Langmuir volume, large Langmuir pressure, large fracture conductivity, large inter-porosity flow coefficient, and large storage coefficient can enhance the production rate and cumulative production of shale gas wells.
- (6) Based on a downhill Simplex algorithm, multiple uncertain parameters can be interpreted well by using the presented multi-rate solutions and multi-pressure solutions. The presented fractal model is well validated by matching real field examples.

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Author Contributions

L. Wang established the novel mathematical model. L. Wang and Z. Dong wrote the main manuscript and prepared all the figures. X.L. provided production data in oil fields. Z.X. designed the computer program. Both X.L. and Z.X. supervised the work and revised the manuscript. All of authors discussed the results and critically reviewed the manuscript.

Additional Information

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