



Publisher Correction: Multi-Modal Mobility Morphobot (M4) with appendage repurposing for locomotion plasticity enhancement

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Check for updates

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The original version of this Article omitted a reference to previous work in ‘Meiri, N. et al. Flying STAR, a hybrid crawling and flying sprawl tuned robot, In 2019 IEEE International Conference on Robotics and Automation (ICRA), 5302–5308 (IEEE, 2019).’ This has been added as reference 44 in the sixth line of the seventh paragraph of the introduction: “However, M4 differs from refs. 42, 43, 44 work because M4 exhaust appendage redundancy manipulation through morphing to maximize locomotion plasticity.” This has been corrected in the PDF and HTML versions of the Article.

The Peer Review File associated with this Article was updated shortly after publication to remove the mistakenly copied article file.

Additional information

Supplementary information The online version contains supplementary material available at <https://doi.org/10.1038/s41467-023-40466-9>.

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