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Damage-free transfer mechanics of 2-dimensional materials: competition between adhesion instability and tensile strain

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Abstract

The transfer of two-dimensional (2D) materials is crucial to the realization of 2D material-based devices for practical applications. The thinness of 2D materials renders them prone to mechanical damage during the transfer process and to degradation of their superior electrical and mechanical properties. Herein, the mechanisms involved in the damage of chemical vapor deposition-grown graphene (Gr) and MoS₂ are investigated during a roll-based transfer process. We identify two different damage mechanisms, i.e., instability-induced damage and tensile strain-induced damage. The two mechanisms compete, depending on the thickness of the transfer medium, and induce dissimilar damage. By minimizing these two mechanisms, we realize and demonstrate the damage-free transfer of 2D materials. The sheet resistance and mobility of transferred Gr are $235 \pm 29 \Omega \text{sq}^{-1}$ and $2250 \text{ cm}^2 \text{V}^{-1} \text{s}^{-1}$, respectively, with no microscopic cracks or tear-out damage. We observe instability-induced damage to be ubiquitous in monolayer MoS₂, thin metals, and thin oxide films. By understanding the instability-induced damage mechanism, a broad range of 2D materials and thin films can be transferred without mechanical damage. Damage-free transfer will contribute to the high-yield fabrication of 2D material-based electronic devices.

Introduction

The transfer of two-dimensional (2D) materials from their growth substrates onto a target substrate is one of the most important step for fabricating 2D heterostructures^{1,2} and 2D material-based devices for practical applications^{3–5}. 2D materials such as graphene (Gr)^{6–8}, MoS₂^{9,10}, and h-BN^{11–13} can be synthesized with high quality on a large scale but are prone to damage when transferred. Transferring large-area 2D materials without any damage is essential for preserving their superior electrical and mechanical properties on a target substrate^{14,15}.

The dry transfer method using a transfer film (TF) is preferred for the large-area transfer of 2D materials because it is readily scalable and compatible with a roll-based continuous transfer process. In 2010, large-area (30-inch) Gr was transferred onto a flexible target substrate using thermal release tape (TRT) as the TF¹⁶. The first practical application of large-area Gr transfer was for a touch panel, but TRT residues and cracks in the transferred Gr were problematic. To overcome these drawbacks, a two-layer TF consisting of a hard supporting film and a thin compliant layer in contact with Gr via dispersive adhesion was suggested^{17,18}. The compliant layer provided conformal contact with the 2D materials, and the supporting layer helped the compliant layer endure the significant deformation that was applied via contact pressure during the roll-based transfer process. The TF was further improved by applying a pressure-sensitive adhesive film (PSAF) as the compliant layer¹⁹.

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The liquid-like PSAF improved the wetting of Gr on the target substrate and had the lowest surface energy, leading to the decreased formation of ripples and cracks. Some roll-based transfer techniques have also been proposed for the reutilization of metal catalysts; these approaches include electrochemical^{20–23} and direct^{24–28} transfer. In these transfer methods, various polymer films that are a few tens of microns thick, such as silicone, ethylene-vinyl acetate (EVA) copolymer, and polyvinyl alcohol (PVA), are used as the compliant layer. However, the Gr transferred by these methods is still structurally damaged and shows degraded electrical properties.

The compliant layer of a TF can significantly mitigate damage to 2D materials when the layer is sufficiently soft for conformal contact²⁹. Notably, the contact and adhesion forces that occur during the transfer process can lead to the deformation of the compliant layer by a strain that is much larger than the failure strain of the 2D material³⁰. Additionally, the compliant layer should have sufficient adhesion to the 2D material to reduce damage during metal catalyst etching and TF lamination. When a 2D material is transferred onto a target substrate, the adhesion should be weaker than that between the 2D material and the target substrate. Most studies to date have focused on increasing compliance to mitigate damage²⁹ and on reducing the surface energy^{18,19} or interfacial energy^{23,31,32} of the compliant layer. However, there are few reports concerning the deformation of the compliant layer that leads to mechanical damage of the 2D material.

Here, we investigate the damage generation mechanisms of 2D materials, such as chemical vapor deposition (CVD)-grown monolayer Gr and monolayer MoS₂, during a roll-based dry transfer process. Contrary to the common belief that damage derives mainly from the interfacial energy difference between Gr and the contacting substrate, we find that the damage is significantly affected by the thickness-dependent deformation behavior of the compliant layer contacting the 2D material. Depending on the thickness of the compliant layer, two different damage mechanisms are found to be involved in damage generation: instability-induced damage and tensile strain-induced damage. In the case of Gr transfer, when the optimal 100- μm -thick polydimethylsiloxane (PDMS) layer is used as the compliant layer, the transferred Gr has the lowest average sheet resistance of $235 \pm 29 \Omega \text{ sq}^{-1}$ for an area of $6 \times 5 \text{ cm}^2$ and the highest mobility of $2250 \text{ cm}^2 \text{ V}^{-1} \text{ s}^{-1}$. We confirm that the instability-induced damage mechanism is also applicable to the transfer of monolayer MoS₂ and various thin metal and oxide films. These results show that by optimizing the thickness of the compliant layer, damage to the 2D materials is significantly reduced, and the original electrical properties of the transferred 2D materials are retained. The proposed transfer mechanics are applicable to the transfer of a

broad range of 2D materials and provide guidance concerning the damage-free transfer of large-area, high-quality 2D materials.

Materials and methods

Sample preparations

Monolayer Gr was synthesized on a 35- μm -thick Cu foil (JX Nippon Mining and Metals Corp., Japan) using the thermal CVD process³³. Monolayer MoS₂ was grown on a 4-inch-diameter wafer with a 300-nm-thick surface-functionalized SiO₂/Si substrate in a 4.3 inch (inner diameter) hot-wall quartz tube MOCVD system³⁴. For the fabrication of the TF, PDMS (Sylgard 184; Dow Corning) and a PET film were used as the compliant layer and supporting film, respectively. Before coating with PDMS, a plasma surface treatment (CUTE plasma system; Femto Science, South Korea) was performed on the PET film to enhance the adhesion between the PDMS and PET film. PDMS was prepared by mixing liquid prepolymer (Sylgard 184 A; Dow Corning, USA) and curing agent (Sylgard 184B; Dow Corning, USA). The mixture was coated as 25-, 50-, 100-, 200-, and 400- μm -thick layers onto the PET film. To prepare the Gr/transfer film (Gr/TF), TF was laminated onto Gr grown on a Cu foil using a home-built roll-to-plate (R2P) transfer machine^{35,36}. The Cu foil was etched with 0.1 M ammonium persulfate (APS) solution or a 0.1 M APS solution containing 5 mM imidazole and 50 mM sulfuric acid (IM-APS)³³. After etching, the TF/Gr film was laminated on the SiO₂/Si substrate under a contact load of 2 N/mm and a lamination speed of 0.5 mm/s using the R2P transfer machine. Prior to the lamination process, various surface treatments were performed on the SiO₂/Si substrate. A plasma surface treatment (CUTE plasma system; Femto Science, South Korea) was used to increase the surface energy of the SiO₂/Si substrate. An amorphous fluoropolymer (Teflon AF 1601; Chemours, USA) was diluted with Fluorinert FC-770 (Sigma-Aldrich, USA) to 0.006 wt%, and the Teflon mixture was coated on the SiO₂/Si substrate to reduce its surface energy. Then, the substrate was baked in an oven at 160 °C for 10 min to remove residual solvent.

Transfer process

The TF was peeled off in two ways. Crack propagation between the Gr and PDMS layer in real time was observed using optical microscopy (OM), in which the TF was slowly peeled off by slightly lifting one end of the TF. During the peeling process, crack propagation was observed and recorded by OM and a charge-coupled device (CCD) camera at a sampling rate of 100 frames/s. For roll-based large-area transfer, the TF was peeled off using the R2P system with precise active load control. In the peeling-off process, the contact load and the peeling-

off velocity were 0.2 N/mm and 0.1 mm/s, respectively. The radius of the roller in the R2P system was 75 mm. Before transferring Gr, the SiO₂/Si substrate was treated with plasma for 30 s (CUTE plasma system; Femto Science, South Korea) to increase the surface energy of the substrate. For the transfer of MoS₂, a TF/MoS₂/SiO₂/Si stack was placed in a deionized (DI) water bath for water-assisted separation. Then, one end of the TF was peeled upward, and crack propagation was observed and recorded by OM and a CCD camera at a sampling rate of 100 frames/s.

Characterization

The adhesion properties of the TF were estimated using a home-built adhesion tester³⁷. A laser-quality fused silica planoconvex lens (PLCX-8.0-25.8-UV; CVI Melles Griot, USA) was used as the counterpart material for the adhesion test. In the test, the contact load was 10 mN, and the dwell time was 100 s. The TF was separated from the lens at a prescribed separation velocity that ranged from 2 to 500 $\mu\text{m/s}$. The contact force and contact area were measured in the test, and the adhesion strength was calculated by dividing the pull-off force by the critical contact area. Raman spectra were obtained using a Raman spectrometer with a 514-nm laser as the excitation source (inVia Raman microscope; Renishaw, UK). The beam size of the laser was 2 μm using a 50 $\times$ objective lens. Images of the transferred Gr were obtained by scanning electron microscopy (SEM, JSM-7610 FPlus field-emission SEM; JEOL, Japan) operating at less than 1 kV to suppress charging. The topography of the samples was investigated using atomic force microscopy (AFM, XE-100; Park Systems, South Korea). A Si probe (NCHR, Park Systems, South Korea) was used to measure the topography over an area of $5 \times 5 \mu\text{m}^2$ at a scan rate of 0.5 Hz. The sheet resistance of Gr was measured in two ways: before the transfer process, the sheet resistance of Gr on a TF was measured using a noncontact resistivity tester (EC-80P; Napson, Japan) with a noncontact probe (NC-5CL; Napson, Japan). The probe contacted the back side of the Gr/TF (i.e., not on the Gr side) to prevent mechanical damage to the Gr surface; after the transfer process, the sheet resistance of the Gr transferred onto the SiO₂/Si substrate was measured using a four-point probe nanovoltmeter (Model 6221; Keithley, USA). The Hall mobility of the transferred Gr was measured using a Hall effect measurement system (HMS-5300; Ecopia, South Korea) at 10 mA.

Finite-element (FE) analysis

The roll-transfer process of Gr was modeled for finite-element analysis in the 2D plane strain condition using ABAQUS commercial code. The steel roll and the flat substrate were considered rigid bodies without any

deformation, and the blanket was firmly attached without slippage. Additionally, we assumed that the 50-mm-wide TF (PET/PDMS) was tightly bonded to the surface of the blanket. The contact condition between the adhesive layer and substrate was deemed frictionless. When the 2 N/mm load from the transfer process was applied, we calculated the strain distribution in the deformable blanket and the TF. Young's modulus and Poisson's ratio of the materials used in the model are listed in Table S1.

Results and discussion

To investigate the damage mechanism of 2D materials, the transfer of CVD-grown monolayer Gr onto an SiO₂/Si wafer was observed in real time using OM and a CCD camera system. Figure 1a illustrates the preparation of a TF sample and a TF/Gr/substrate (SiO₂/Si) stack sample. The compliant layer of the TF was formed by coating a thin PDMS layer onto a polyethylene terephthalate (PET) film. A home-built R2P transfer machine with active load control was used for all lamination processes^{35,36}. The TF/Gr/substrate stack was placed on the microscope stage, and the TF was slowly peeled from one end of the TF (Fig. 1b). Figure 1c shows real-time OM images of the propagation of the interfacial crack front as the TF was peeled from the substrate. The shape of the interfacial crack front varied greatly and depended on the thickness of the PDMS layer (25, 100, or 400 μm) (Movie S1, Supporting Information); additionally, the PDMS surface energy was constant (Fig. S1, Supporting Information). After the complete removal of the TF, the transferred Gr on the SiO₂/Si wafer was observed again using OM and SEM. Figure 1d, e shows that the shape of the damage depended on the thickness of the PDMS layer. Notably, for the transfer using a 100- μm -thick PDMS layer, no structural damage was observed over an area of a few tens of square centimeters. In contrast, when the thickness of the PDMS layer was 25 or 400 μm , the transferred Gr was severely cracked and torn. Raman spectroscopy and AFM confirmed that there was no Gr in the damaged areas (Fig. S2, Supporting Information). Using TFs with different PDMS layer thicknesses enabled large-area Gr to be transferred onto the SiO₂/Si substrate under well-controlled transfer conditions using the R2P transfer machine (Fig. 1f). Figure 1g shows a histogram of the sheet resistance of the transferred Gr according to the thickness of the PDMS layer. The average sheet resistance of Gr was the lowest when the thickness of the PDMS layer was 100 μm , at $235 \pm 29 \Omega \text{sq}^{-1}$; the inset of Fig. 1g shows that the sheet resistance was quite uniform over an area of $6 \times 5 \text{cm}^2$ (Fig. S3b, e, Supporting Information). On the other hand, when the thickness of the PDMS layer was 25 or 400 μm , the average sheet resistance of Gr was higher at 1130 ± 42 and $563 \pm 202 \Omega \text{sq}^{-1}$, respectively. The distribution of the sheet resistance was severely nonuniform (Fig. S3a, c, Supporting Information), even when the same

Fig. 1 Mechanical damage of the transferred graphene (Gr) induced by the thickness-dependent deformation of the PDMS layer.

a Schematic illustration showing the preparation of the transfer film (PET/PDMS)/Gr/substrate (SiO_2/Si) stack. Samples were prepared with different thicknesses of the PDMS layer in the TF. The lamination process was performed using a roll-to-plate (R2P) transfer machine with active load control. **b** Schematic illustration showing the transfer test used to observe the interfacial crack front in real time using optical microscopy (OM). **c** In situ OM images of the interfacial crack front during the peeling process for TFs having different PDMS layer thicknesses ($t = 25$, 100, and 400 μm). The interfacial crack front propagated from right to left within 1 s. After completely peeling off the TF, the transferred Gr on the substrate was observed using **d** OM and **e** scanning electron microscopy (SEM). The optical microscopy and SEM images showed the difference in structural damage to the transferred Gr according to the thickness of the PDMS layer. In the case of the TF with a 100- μm -thick PDMS layer, structural damage was hardly visible in the transferred Gr. The scale bars in **c**, **d**, and **e** represent 200 μm . **f** Photograph of the R2P transfer machine used to transfer large-area Gr onto the SiO_2/Si substrate using the TFs. **g** Histogram of the sheet resistance of the transferred Gr. The histogram showed that the sheet resistance of the Gr transferred using the TF containing a 100- μm -thick PDMS layer had the lowest value and was uniform over an area of $6 \times 5 \text{ cm}^2$ (inset).

transfer conditions were used. This higher sheet resistance was likely responsible for the structural damage generated during the roll-transfer process. Scanning electron

microscopy images of Gr transferred by the R2P machine show the different damage shapes that depended on the PDMS thickness (Fig. S3d–f, Supporting Information).

The trend in shape in relation to thickness resembles that shown in Fig. 1d, e. These results confirm that the thickness of the PDMS layer used as the compliant layer was one of the main causes of damage in both the laboratory-scale manual transfer and the roll-based large-area transfer of Gr. Thus, careful attention should be given to the thickness of the compliant layer to avoid mechanical damage to the transferred Gr. Therefore, the quality of transferred Gr could be significantly improved merely by adjusting the compliant layer thickness. The following paragraphs detail the effect of the compliant layer thickness on the damage generation mechanism.

As the thickness of the PDMS layer decreased below 100 μm , the shape of the interfacial crack front during TF peeling changed into a complex shape resembling fingers and ripples. This behavior is characteristic of the adhesion-induced instability of a confined thin film³⁸. When a thin compliant layer with a shear modulus of less than 10 MPa is peeled off, thinner layers are more inclined to deform laterally than thicker layers; thus promoting instability to release the elastic strain energy stored in the film^{39,40}. The shape of the instability is predominantly influenced by the layer thickness, rather than the material

properties and the surface energy of the contacting materials^{40–42}. To quantify the instability, we defined the instability ratio (Λ) as the overall length (L) of the interfacial crack front divided by the reference length (L_0) ($\Lambda = L/L_0$, inset of Fig. 2a). For example, the instability ratio was 1 when there was no instability in the interfacial crack front. Figure 2a shows that the instability ratio increased rapidly with a decreasing PDMS thickness, especially below a thickness of approximately 50 μm . The elastic modulus of the PDMS significantly changed with the mixing ratio, while the surface energy of the PDMS layer was unchanged (Fig. S4, Supporting Information). The surface treatments greatly changed the surface energy of the SiO₂/Si substrates. Our findings revealed that the instability ratio was affected mainly by the PDMS thickness, while the elastic modulus of the PDMS and the surface energies of the substrate rarely affected the instability ratio.

To investigate the relationship between instability and damage to the transferred Gr, we superimposed the OM images of the interfacial crack front captured every 1 s during the transfer process onto the image of the transferred Gr observed at the same location after completely

peeling off the TF (Fig. 2b). Figure 2c shows the resultant superimposed images for the PDMS layers with different thicknesses and reveals that the shape of the damage generated on the transferred Gr coincides well with the propagation shape of the instability in the PDMS layers for layer thicknesses of 25 and 50 μm . Regarding these layers, the interfacial crack front at the end of the fingers propagated much faster (Fig. S5, Supporting Information), despite the slow peeling speed of the TF; therefore, the damage spread along the propagation direction of the instability. However, when the thickness was 100 μm , some instability occurred, but not severely, and no structural damage was evident on the transferred Gr. Figure 2d shows the measured adhesion strength of the PDMS layers as a function of separation velocity. As the separation velocity increased, so did the adhesion strength, indicating that the adhesion characteristics of the PDMS layer were rate-dependent^{25,37,43,44}. The increase in adhesion strength was more substantial for PDMS layers thinner than 100 μm . Due to the instability, the PDMS layer rapidly separated from the substrate at the end of the fingers. The adhesion between the layer and Gr was significantly higher due to the rate-dependent

adhesion characteristics of the layer. The increased adhesion tore Gr from the substrate, corresponding to the propagation shape of the instability. In addition to thin PDMS layers, some commercially available TFs with 25- μm -thick silicone or 80- μm -thick EVA layers as the compliant layer can also cause instability-induced damage to transferred Gr (Fig. S6, Supporting Information). Therefore, for a PDMS layer thinner than 100 μm , the damage to the transferred Gr was mainly caused by instability. In addition, the 100- μm -thick PDMS layer left little residue on the transferred Gr compared to the commercial TFs (Fig. S7, Supporting Information).

When the thickness of the PDMS layer exceeded 150 μm , the instability ratio was almost 1 (Fig. 2a), indicating the absence of instability. However, crack-like damage, which was not caused by instability, was observed on the transferred Gr when the thickness of the PDMS layer was 400 μm (Fig. 1d, e and Fig. S3f, Supporting Information). To investigate the damage mechanism for the thick PDMS layers, finite-element models (FEMs) were developed to simulate the mechanical contact that occurred during the roll-transfer process for PDMS thicknesses of 100, 200, and 400 μm . Figure 3a illustrates

Fig. 3 Finite-element analysis of the roll-to-plate (R2P) transfer process and simulated strain distribution according to PDMS layer thickness. **a** Schematic illustration showing the finite-element model; the transfer film (PET/PDMS) was fixed on a soft blanket, and the PDMS layer came into contact with the rigid substrate under a contact load of 2 N/mm. **b** Contours of the in-plane strain ϵ_x along the circumferential direction of the roll according to the PDMS layer thickness. The PDMS layer experienced maximum tensile strain near the end of the contact area. **c** Profiles of the in-plane strain ϵ_x in the PDMS layer surface as a function of thickness. The critical failure strain of Gr/PET was approximately 0.6%^{45,46}.

the FEM used to calculate strain distributions. A 1-mm-thick soft blanket was wrapped around a rigid stainless-steel roll with a radius of 75 mm, and the TF (PET/PDMS) was fixed on the blanket without slippage. Since the blanket had a lower elastic modulus than that of the PDMS, it was possible to avoid nonuniform contacts caused by mechanical misalignment in the R2P machine. The analysis was performed for PDMS layer thicknesses of 100, 200, and 400 μm . The blanket/PET/PDMS layer stack deformed when in contact with a rigid substrate when the applied contact load per unit width was 2 N/mm; this parameter was equal to the experimental condition of R2P lamination. The mechanical properties, layer thicknesses, boundary conditions, and calculation details are described in the Methods section and Table S1 of the Supporting Information. Figure 3b shows the contour of the in-plane strain ϵ_x along the circumferential direction of the roll according to the thickness of the PDMS layer. The soft, thick blanket was largely deformed along the circumferential direction by the contact pressure, while the PET supporting film with a relatively large elastic modulus was hardly deformed, and the strain of the blanket was not transferred to the PDMS layer. However, the thin PDMS layer deformed significantly near the contact area between the layer and substrate because of the deformed geometries in the layered structure. At the contact edge, the radius of curvature of the PDMS surface abruptly converted from a finite to an infinite value, which resulted in tensile deformation in the thickness direction. Hence, compressive deformation in the circumferential direction at the contact edge occurred due to Poisson's effect, which resulted in tensile deformation in the adjacent region of the contact edge. This phenomenon was also observed in the transfer process when a roll coated with a thin and deformable film was used^{35,36}. In this study, the larger area over which the sudden fluctuation of ϵ_x in the PDMS layer increased with an increasing thickness was due to the geometric effect. Figure 3c shows the variation in strain ϵ_x at the PDMS surface as a function of the circumferential distance from the center. The 100- μm -thick PDMS layer experienced a maximum tensile strain of $\sim 0.6\%$ near the end of the contact area. As the thickness increased to above 200 μm , the maximum tensile strain increased by more than 0.7%, which exceeded the critical failure strain of the CVD-monolayer Gr transferred onto the PET film. Previous research established that Gr started to crack along the direction perpendicular to the applied tensile strain, and the resistance of the Gr/PET increased accordingly when the tensile strain exceeded 0.6%^{45,46}. The FEM analysis indicated that when the thickness of the PDMS layer exceeded 100 μm , the maximum tensile strain in the PDMS layer caused by the contact pressure exceeded the failure strain of the CVD Gr, causing the Gr to crack. This mechanism

explained why crack-like damage was observed mainly for the Gr transferred via the 400- μm -thick PDMS layer and why the damage had a different shape than the instability-induced damage on the Gr transferred via the 25- μm -thick PDMS layer (Fig. 1c, d).

As explained above, the damage mechanism depended on the thickness of the PDMS layer in contact with Gr. The electrical properties of the transferred Gr also changed with the PDMS layer thickness. Figure 4a shows the change in the sheet resistance of Gr before and after the R2P transfer process. As the PDMS layer thickness decreased below 80 μm , the relative sheet resistance increased significantly due to increased instability-induced damage, regardless of the mixing ratio of the PDMS. As the thickness of the PDMS layer increased above 150 μm , the relative sheet resistance gradually increased due to increased tensile strain-induced damage. Therefore, there was an optimal layer thickness that minimized both damage mechanisms. When the thickness of the PDMS layer made at a mixing ratio of 10:1 ranged from 90 to 150 μm , the change in the sheet resistance of Gr before and after the R2P transfer process was less than 10%. The same trend was noted in the mobility measurement (Fig. 4b). Similar to the observed changes in sheet resistance, the mobility also increased rapidly with an increasing PDMS thickness, with a maximum mobility of 2250 $\text{cm}^2 \text{V}^{-1} \text{s}^{-1}$ recorded at a PDMS thickness of 100 μm . Then, the mobility gradually decreased with an increasing thickness. The 2D and D peaks of the transferred graphene without mechanical damage were comparable to those of the as-grown graphene in the mapping area. (Fig. S8, Supporting Information). Figure 4c summarizes the damage mechanisms that depended on the compliant layer thickness. In the case of a compliant layer that was thin enough to cause adhesion instability, the propagation velocity of the interfacial crack front increased locally at the end of the fingers. In this region, the adhesion between the layer and Gr was enhanced by the rate-dependent adhesion characteristics of the layer, allowing the Gr to adhere to the layer and not transfer onto the substrate. As the thickness of the compliant layer increased, the adhesion instability disappeared, but the compliance of the layer increased in proportion to the thickness. Therefore, when the tensile strain of the layer along the circumferential direction of the roll due to contact pressure exceeded the failure strain of Gr at the edge of the contacted area, Gr cracked perpendicularly to the rolling direction. A TF for damage-free transfer should be carefully designed because the mechanical properties and thickness of the materials comprising the TF can alter the tensile strain of the compliant layer.

The instability-induced damage mechanism is applicable to MoS_2 transfer as well as to Gr transfer. MoS_2 was grown on a SiO_2/Si wafer using the metal-organic chemical vapor

deposition (MOCVD) process³⁴ and confirmed to be a monolayer (Fig. S9, Supporting Information). Figure 5a shows the transfer process of monolayer MoS_2 from the growth substrate to the TF using water-assisted separation. Transfer films with different PDMS thicknesses were laminated onto the MoS_2 samples using the R2P transfer machine. The resulting TF/ MoS_2 samples were then placed in a deionized (DI) water bath to enable water penetration at the MoS_2 /substrate interface^{34,47,48}. When the end of the TF was peeled upward, the MoS_2 separated from the substrate, and interfacial crack propagation was observed in real time by OM (Fig. 5b and Movie S2, Supporting Information). In the case of the TF with the 25- μm -thick PDMS layer, severe adhesion instability occurred at the interfacial crack front during the separation process. In contrast, in the case of the TF with the 100- μm -thick PDMS layer, such severe instability did not occur. The surfaces of the TF and the substrate were observed after complete separation. Figure 5c shows that when the thickness of the PDMS layer was 25 μm , MoS_2 was partly transferred onto the PDMS surface in the shape of the propagated instability. The rest of the MoS_2 remained exactly on the substrate but in the reverse shape

(Fig. 5d). When the PDMS layer was 100 μm thick, instability-induced damage did not occur during separation, and MoS_2 was transferred well from the substrate to the PDMS layer. Figure 5e, f shows AFM images of the MoS_2 that remained on the substrate and the Raman mapping of the A_{1g} peak for the specified area. When the MoS_2 /substrate was peeled off by a TF with a 100- μm -thick PDMS layer, the MoS_2 was clearly removed in most areas, and the MoS_2 remaining on the substrate was observed only at the edge of the contacted area (Fig. 5e). In contrast, when MoS_2 was transferred by the 25- μm -thick PDMS layer, MoS_2 was peeled off with a sharp saw-tooth shape at the edge of the delaminated area along the direction of the propagated instability (Fig. 5f). The Raman mapping data of the A_{1g} peak at the specified areas revealed that MoS_2 remained uniformly on the substrate after delamination. In addition, it was confirmed by photoluminescence (PL) mapping that the crystal quality of the transferred MoS_2 was not degraded when MoS_2 was transferred by the transfer film with 100 μm -thick PDMS (Fig. S10, Supporting Information).

As noted above, instability-induced tear-out damage and tensile-strain-induced crack-like damage of the transferred

2D materials were closely connected to the thickness-dependent deformation behavior of the compliant layers. In addition, the thickness of the compliant layers affected the conformal contact between the layer and 2D materials because the compliance of the layers decreased with decreasing layer thickness^{29,49}. However, most research concerning the transfer of 2D materials using a TF with a thin compliant layer, such as silicone^{17–19}, EVA^{20–24,26}, PVA²⁸, and PDMS^{6,44}, did not give attention to the compliant layer thickness or its deformation behavior under transfer conditions. Consequently, the quality of transferred 2D materials often varies between research groups because of differences in the compliant layer thickness, even when almost the same transfer method is used. The damage mechanism according to the thickness-dependent deformation behavior of the compliant layer was not limited to the transfer of 2D materials and could be extended to the transfer of various thin films, such as metal and oxide layers. Transferring several tens of nanometer-thick thin films of Au and Al-doped ZnO (AZO) using a TF with a 25-μm-thick PDMS layer led to instability-induced damage (Fig. S11, Supporting Information). In addition

to the compliant layer thickness, the contact load applied to the TF/2D materials/substrate stack was another critical factor that should be carefully controlled to achieve conformal contact between 2D materials and the substrate and reduce the tensile strain-induced damage of 2D materials in the lamination and transfer processes (Fig. S12, Supporting Information). In most previous studies, large-area Gr was transferred using a simple laminator system^{16,18,26}, which was typically operated with spring-loaded rollers without active load control. When using the system, the contact pressure and resultant tensile strain in the compliant layer could vary greatly depending on the total thickness of the stacked sample. Therefore, to improve the transfer yield, careful attention must be given to the thickness of the compliant layer in contact with the 2D material and the contact load applied to the stacked sample during the entire transfer process.

Conclusions

In conclusion, we found that the thickness-dependent deformation behavior of a thin compliant layer in a TF played a crucial role in controlling the damage to 2D

materials during the transfer process. The two damage mechanisms of instability-induced damage and tensile strain-induced damage had a tradeoff relationship with respect to the thickness of the compliant layer. This result meant that there was an optimal thickness that minimized the overall damage. By optimizing the thickness of the compliant layer, the damage-free transfer of 2D materials could be achieved. Herein, when we used the optimal 100- μm -thick PDMS layer, the transferred Gr had the best quality and was free of cracks and other damage. The sheet resistance and mobility of the transferred Gr were $235 \pm 29 \Omega \text{sq}^{-1}$ and $2250 \text{cm}^2 \text{V}^{-1} \text{s}^{-1}$, respectively. No degradation was observed in the sheet resistance before and after the transfer process, indicating that the transferred Gr was damage-free. We observed instability-induced damage ubiquitously in monolayer MoS_2 , thin metal films, and thin oxide films. Understanding the instability-induced damage mechanism enables the damage-free transfer of a broad range of 2D materials and thin films onto arbitrary substrates. These findings will facilitate the high-yield fabrication of 2D material-based electronic devices.

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Conflict of interest

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