

PERSPECTIVE

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# Self-healing materials for soft-matter machines and electronics

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## Abstract

The emergence of soft machines and electronics creates new opportunities to engineer robotic systems that are mechanically compliant, deformable, and safe for physical interaction with the human body. Progress, however, depends on new classes of soft multifunctional materials that can operate outside of a hard exterior and withstand the same real-world conditions that human skin and other soft biological materials are typically subjected to. As with their natural counterparts, these materials must be capable of self-repair and healing when damaged to maintain the longevity of the host system and prevent sudden or permanent failure. Here, we provide a perspective on current trends and future opportunities in self-healing soft systems that enhance the durability, mechanical robustness, and longevity of soft-matter machines and electronics.

## Introduction

Engineering machines and electronics to be smaller, lighter, and less rigid enables them to better integrate into the environment and interact with humans. Such progress has the potential to revolutionize fields such as personal computing and health care by introducing new classes of textiles with digital circuit functionality, epidermal stickers for wireless biomonitoring, and soft robotic systems capable of human motor assistance or therapy. However, removing the hard exterior and making machines and electronics soft and lightweight introduces challenges in design since the materials are required to be simultaneously durable, tough, and load bearing as well as mechanically compliant and deformable. This requirement introduces a potential dilemma in materials engineering that arises from the typical tradeoff between strength and compliance<sup>1</sup>, which is also common in natural materials and organisms. In nature, organisms address this apparent tradeoff with passive architectures that combine soft and rigid materials with functionally

graded interfaces and active mechanisms, such as reversible rigidity tuning and self healing. However, while there has been significant recent attention paid to the rigidity tuning<sup>2</sup> and self-healing ability of naturally stiff polymers and composites<sup>3</sup>, there has been considerably less attention paid to how self-healing materials can also be used to make soft material systems more mechanically robust.

From this perspective, we present an overview of the current progress in self-healing materials that can enable soft-matter machines and electronics to support more extreme mechanical loading without catastrophic failure. This overview includes a working definition of “self-healing” within the context of soft material systems and examples related to structural materials, electronics, and robotic systems, as distinguished in Fig. 1. More broadly, these material architectures fall under an increasingly growing family of soft bioinspired systems for sensing, circuit wiring, and actuation that exhibit many of the same robust mechanical properties as their natural tissue counterparts. These systems are fabricated using a wide variety of materials and manufacturing methods, from deterministically patterned thin-film wavy electronics produced using cleanroom fabrication methods to soft microfluidics and biohybrid systems created using wet-lab soft lithography techniques. As these soft-matter

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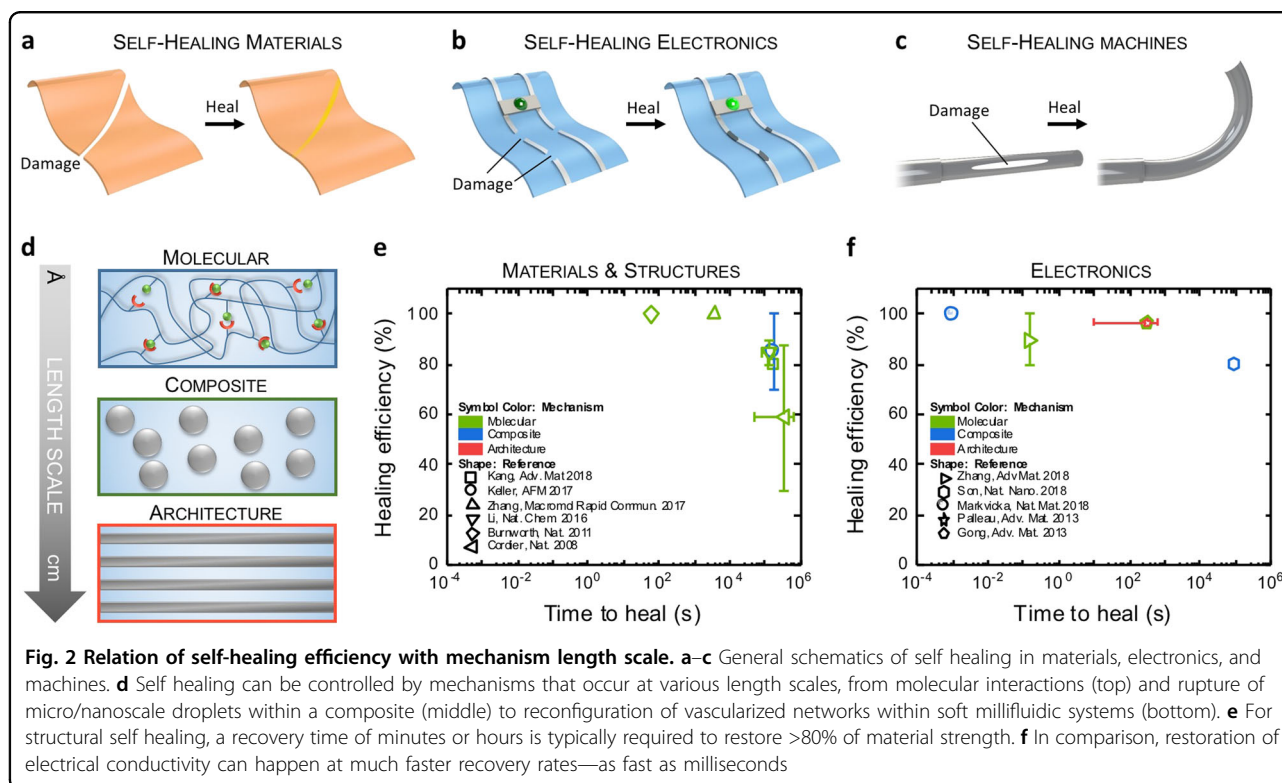
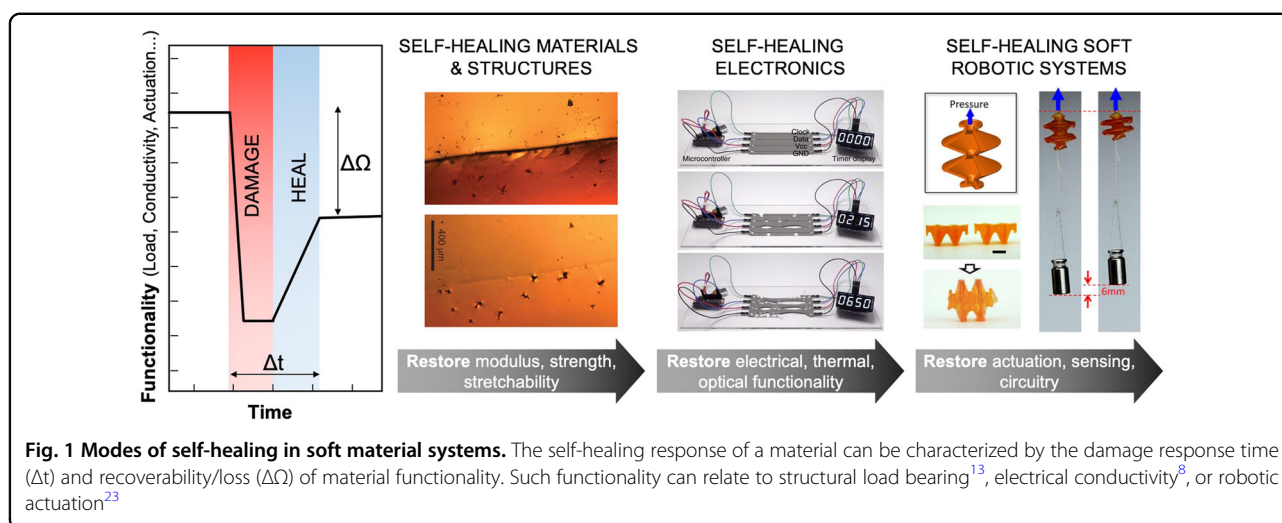
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technologies leave the lab and enter real-world environments, they must be further refined or re-engineered so that they can withstand not only stretching, bending, and twisting but also scrapes, cuts, and punctures.

### Mechanisms

Broadly speaking, self healing can relate to a variety of properties and active responses observed in materials, electronics, and machines (Fig. 2a–c). The underlying mechanisms for self-healing materials and electronics

involve the reestablishment of mechanical or electrical contact, which can occur across a range of length scales (Fig. 2d). Molecular mechanisms utilizing dynamic bonds (secondary, covalent, and supramolecular bonds) have been effective in soft materials such as hydrogels, solvent- or moisture-activated systems, and materials above their glass transition temperature<sup>4–6</sup>. When a material is damaged, the molecular networks are severed. Heat or solvents can assist in reforming these networks through molecular rearrangement and can improve molecular

mobility to reduce healing time. At the meso- and microscales, self healing is enabled within composite systems through the use of functional particles such as microcapsules filled with liquids, micro/nanodroplets, and solid fillers<sup>7,8</sup>. When a composite system is damaged, microcapsules release healing agents, microdroplets rupture and coalesce, forming new connections, and solids reestablish contact at time scales dependent on the network mobility. Finally, submillimeter- to centimeter-scale architectures of channels and vascular networks filled with functional fluids can enable self healing<sup>9–11</sup>. Upon damage, these networks reform through rearrangement of material connectivity or can be manually restored to reestablish the preexisting networks. These techniques can be evaluated by a few critical metrics, which include the following: healing efficiency (defined as  $100 \times [\text{healed strength}/\text{original strength}]$ ), time to heal, and environmental conditions required for healing.

## Examples and applications

### Self-healing materials and structures

Creating materials that are strong, soft, deformable, and self healing presents a challenge. One approach has been the use of supramolecular structures with hydrogen bonding. This method has been demonstrated with elastomers that heal under ambient conditions through the rupture and reformation of dynamic hydrogen bonds and coordination complexes<sup>4,12,13</sup>. Double-network structures with hydrogen bonding can create tough and extensible materials that can heal in the presence of artificial sweat<sup>5</sup>. Microcapsule approaches have also been demonstrated, in which a PDMS elastomer filled with microcapsules of resin and crosslinker rupture and flow when damaged<sup>7</sup>. Self-healing PDMS has also been accomplished with a triformylbenzene crosslinker that reacts with polymer chains through reversible imine bonds<sup>14</sup>. The tradeoff in these approaches is between the time and temperature used for self healing, where lower temperatures require longer times. An approach to overcome this limitation is the use of ultraviolet light to promote local healing<sup>6</sup>. These examples have all demonstrated the potential to achieve healing efficiencies of  $\sim 100\%$ ; however, external intervention or extended time scales are still required to achieve self healing (Fig. 2e).

### Self-healing electronics

Self-healing electronics exhibit the ability to maintain or recover their high electrical performance and robust mechanical functionality when damaged. Molecular processes have been demonstrated with conductive polymers, such as poly(3,4-ethylenedioxythiophene) polystyrene sulfonate (PEDOT:PSS), and semiconducting polymers, where droplets of water or solvent have been shown to restore conductivity to cut films<sup>15,16</sup>. While these composites have a modulus above the 10 MPa threshold

typical for soft materials, effective compliance can be achieved at the system/device level by incorporating the composites as thin films on a soft elastomer substrate. Self healing with soft ionically conductive materials has been demonstrated through reversible ion-dipole interactions of ionic gels<sup>17</sup>. Reversible ionic interactions also contribute to the self healing of an electrically conductive hydrogel containing polypyrrole and ferric ions<sup>18</sup>. Composites with rigid fillers or thin-film coatings have been demonstrated with high-aspect-ratio nanoparticles, such as silver nanowires (AgNWs) and carbon nanotubes (CNTs). With AgNW coatings, self healing is accomplished by using a polymer substrate capable of a reversible Diels-Alder (D-A) reaction<sup>19</sup>. For CNTs, a dynamically crosslinked polymer matrix with low glass transition temperature is postulated to contribute to the reconstruction of the damaged network<sup>20</sup>. Microdroplets of liquid metal dispersed in soft elastomers have been shown to rupture upon damage to autonomously form new connections with neighboring droplets and reroute electrical signals. As the droplets merge during the damage event, electrical conductivity is continuously maintained, and no external intervention is required<sup>8</sup>. Channel networks have been demonstrated by incorporating microfluidic channels filled with liquid metal into supramolecular elastomers<sup>9</sup>. Here, the materials can be cut and pressed back into contact, and mechanical and electrical self healing can be obtained. These examples highlight some of the approaches in restoring electrical functionality when a material has been damaged. Referring to Fig. 2f, this process can happen much more rapidly than the restoration of structural functionality. However, challenges remain in incorporating electrical and mechanical self-healing systems that maintain functionality during damage and heal at rapid time scales.

### Self-healing soft robotic systems

Advances in self-healing materials and electronics can enable self-healing robotic systems and actuators. Building on the molecular mechanisms in self-healing materials, thermoreversible Diels-Alder chemistry has been utilized to heal pneumatic actuators<sup>21</sup>. Self-healing electrical wiring realized using liquid metal microdroplets dispersed in elastomers can drive shape memory alloy (SMA) actuators, where the robot continues to function after sections of the wiring are removed<sup>8</sup>. Self healing has also been leveraged in dielectric elastomer actuators, where fluidic dielectric layers can self heal after dielectric breakdown. This property allows the actuator to be reused over multiple cycles, in contrast to solid dielectrics, which fail after a single breakdown<sup>11</sup>. On the millimeter-centimeter scale, soft actuators have been incorporated with tough fabrics to increase tear resistance, while the soft compliance of elastomers allows self healing of small

punctures<sup>10</sup> and shape recovery after extreme, recoverable deformations<sup>22</sup>. Self healing in soft robotics is challenging due to the integration of multiple materials and technologies, from elastomeric pneumatic actuators to fluidic sensing electronics and rigid electronic components, which present multiple failure locations. Future opportunities include self healing at diverse material interfaces, monitoring damage in soft systems, and creating robots that can actively repair themselves.

### Future directions

While there has been tremendous progress in recent years, there remain exciting opportunities for further advancements in the development of damage-tolerant material systems that support mechanically robust structural, electronic, and robotic functionality. These systems include materials with “embodied intelligence” capable of detecting damage, reporting the event, and healing or adjusting material properties and geometry to mitigate the damage to avoid failure or future damage. Such functionality will require the tunability of the healing response—i.e., controlling variables, such as the repair time, the properties of the resulting repaired system, and how much of the material is healed. Intelligent material response could also be accomplished through system adaptation, where undamaged regions of the material could reconfigure to transfer the mechanical or electrical functionality to unaffected regions. Furthermore, the issues of repeatability (fatigue) and reversibility (recovery) need to be addressed. If damage is sustained in an already damaged or repaired area, how can materials and structures be designed to enhance the strength, toughness, or stiffness of that region over multiple damage cycles? Lastly, actuation and power mechanisms should be considered, where low-voltage electrical operability can provide benefits over thermal, photonic, pneumatic, or hydraulic systems in terms of mass, power consumption, response speed, and programmability of the supporting hardware. Advancements in these areas could provide significant benefits to the robustness and damage tolerance of diverse soft technologies, enabling new generations of human-compatible electronics and robotics for applications ranging from health care and computing to augmented performance and human-machine interfaces.

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The authors declare that they have no conflict of interest.

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