



# Mechanical properties of doubly crosslinked gels

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## Abstract

We fabricated the doubly crosslinked gel, with internal stress by stretching the gel during the gelation reaction using tetra-PEG gels, which are formed by the AB type crosslink-coupling of two mutually reactive tetra-arm polyethylene glycol (PEG). In a doubly crosslinked gel, two networks having different reference states coexist with and balance each other, resulting in enhanced Young's modulus and residual strain. We investigated these properties by tuning the time for the imposition of the stretching of the gels and the stretching ratio. The residual strain increased with increase in the time for the imposition of stretching and the stretching ratio. On the other hand, the Young's modulus had a maximum value at a certain time for the imposition of the stretching of the gels and increased with increasing stretching ratio. These results were well explained by the balance between the strain energies of the first and second networks under the framework of the classical two-network theory, where the total strain energy is described as a simple sum of the energies of the first and second networks.

## Introduction

Anisotropic mechanical materials exist widely in nature. For example, skeletal muscles have fibrous structures and exhibit contraction-elongation motion along the fiber axis. Elastomeric materials, including muscles, exhibit reversibly large deformability and markedly nonlinear stress-elongation relationships with small stress stemming from the entropic elasticity. Anisotropic responses become significant when the anisotropic moieties are trapped in these soft elastomeric matrices. There have been many attempts to introduce anisotropic structures in the elastomeric matrices. Such structures are installed by introducing anisotropically aligned moieties, including the liquid crystal mesogen [1–4] and carbon nanomaterials [5, 6], with external mechanical,

magnetic, and electric fields. In addition to introducing moieties with a high aspect ratio, one can introduce anisotropy by chemical crosslinking under an external mechanical field such as uniaxial extensional flow. Materials formed by this type of method have been referred to as “double-network rubbers” for more than half a decade. The double-network rubbers are crosslinked twice: crosslinking in an initial nondeformed state first and subsequently crosslinking in a deformed state. The initial stretched network is pinned by the second network, resulting in the mechanical and optical anisotropies. Notably, these materials are different from the “double-network gels” developed by Gong et al., which are formed by two different monomeric networks, a rigid and brittle one and a soft and ductile one. Here, we use the term “doubly crosslinked gels” to avoid confusion.

Until now, many studies have been carried out on the doubly crosslinked gels. Tobolsky et al. first introduced the double crosslinking concept to explain the physical aging of rubbers, which involved free-radical scission and crosslinking under deformation [7, 8]. After that, many researchers studied the physical properties, such as mechanical properties, of the doubly crosslinked gels [9–14]. The mechanical properties and permanent set of doubly crosslinked gels were discussed based on the “two-network theory” proposed and developed by Berry et al. [9], Flory [15], and Fricker [16]. In the two-network theory, the elastic free energy ( $W$ ) for the doubly crosslinked gel is

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expressed merely as the sum of the first ( $W_1$ ) and second ( $W_2$ ) networks.

$$W = W_1 + W_2 \quad (1)$$

$W$  is determined by the deformation ratio relative to the state of “reference”, which generally corresponds to the state where the crosslinking is introduced. In the two-network theory, the reference state is different from either the first or second network. The residual strain and Young’s modulus are determined by the balance between the first and second networks.

However, the quantitative understanding of these properties remains incomplete mainly due to three reasons. The first problem is the viscoelastic property, which is a feature of general rubbers. After the imposition of stretching with high strain rate, the stress and the orientation of the first networks reduces with time. The stretching rate and the second crosslinking reaction rate strongly influence the orientation of the first networks. Thus, the balance between the viscoelastic relaxation and the crosslinking reaction rate determines the orientation of the first network strands in the resultant networks, which deviates the situation from the simple concept represented by Eq. 1.

The second problem is the difficulty of independently controlling the network structures, such as the network strand length and the functionality of the crosslinking point. Conventional elastomers have many inhomogeneities, including spatial and connectivity heterogeneities and trapped entanglements [17]. These inhomogeneities are uncontrollable and preclude the systematical understanding of the relationships between the network structures and the strain energy density ( $W$ ) function. In addition, general rubbers exhibit the significant strain-softening effect under uniaxial stretching, which cannot be explained by the classical rubbery theory [18–21]. Although this softening behavior is phenomenologically described by the complex  $W$  function with higher-order terms of the first and second invariants of the Green’s deformation tensor [22–28], this deviation hinders the correct estimation of the first and second network components of  $W$ .

The third problem is the coupling of the  $W$  function and connectivity. Pioneering works assumed that the  $W$  function of the first and second networks is identical to the network formed without any deformation. However, in a conventional crosslinking process, the formation of crosslinks decreases the network strand length, resulting in a decrease in the maximum stretching ratio. Furthermore, crosslinking freezes the topological constraints by entanglements, which contributes to elasticity [29, 30]. Although there have recently been some attempts to assess the effects of these topological effects on the doubly crosslinked networks by molecular dynamic simulation [31, 32], separating these effects experimentally is still difficult.

Because of these difficulties, the experimental examination of the two-network theory is limited. To overcome these problems, a system with little viscoelastic effect and good controllability over network structures is necessary. Gels are promising for avoiding the viscoelastic effect because dilution generally reduces the entanglements and enhances the molecular motion. Even for gels, however, the uncontrollability of the network structures remains a long-standing problem.

Recently, we have successfully designed and fabricated a “tetra-PEG gel”, which forms nearly ideal networks [33–35]. Tetra-PEG gels are formed by the AB type crosslink-coupling of two mutually reactive tetra-arm polyethylene glycol (PEG). In the small angle neutron scattering (SANS) measurement, we observed no appreciable degree of excess scattering relative to that of the uncrosslinked PEG solutions with the same concentration, suggesting that practically no spatial inhomogeneity exists in regions up to 200 nm in size [36]. Investigation of infrared spectroscopy (IR) showed that the reaction conversion is up to 0.9 [37–39]. Nuclear magnetic resonance (NMR), investigation of small deformation and fracture testing showed that the elastically active junctions are merely governed by chemical crosslinks, whereas the contribution of entanglements between the network strands and elastically ineffective loops are small [37, 38, 40]. A tetra-PEG gel has high reaction conversion, few elastically ineffective loops, and trapped entanglements and thus is a promising system for evaluating the physical properties of polymer gels. The  $W$  function of the tetra-PEG gels can be ideally approximated in the small-deformation region by the classical rubber elasticity theory [38, 41]. In addition, above a certain degree of connectivity, the stress-strain curves of the tetra-PEG gel normalized by the shear modulus are independent of connectivity [42]. These previous works suggest that the tetra-PEG gel is a promising material for the examination of the two-network theory.

In the present study, we fabricated doubly crosslinked gels using the tetra-PEG gels. We measured the residual strain and the mechanical properties of the samples with various time for the imposition of the stretching of the gels during gelation ( $t_i$ ) and the imposed elongation ratios ( $\lambda_i$ ). Based on the obtained data, we experimentally examined the validity of the two-network theory.

## Materials and methods

### Materials

Tetra-amine-terminated PEG (Tetra-PEG-NH<sub>2</sub>) and tetra-succinimidyl ester (OSu)-terminated PEG (Tetra-PEG-OSu) were purchased from NOF Co. (Tokyo, Japan). Details of Tetra-PEG-NH<sub>2</sub> and Tetra-PEG-OSu preparation have been previously reported [33]. The molecular weights of the prepolymers ( $M_{pre}$ ), Tetra-PEG-NH<sub>2</sub> and Tetra-PEG-OSu,

were equal to each other ( $M_{\text{pre}} = 20$  kg/mol). Equal amounts of Tetra-PEG-NH<sub>2</sub> and Tetra-PEG-OSu (100 g/L) were dissolved in phosphate buffer (pH 7.4) and phosphate-citric acid buffer (pH 5.8), respectively. The corresponding initial polymer volume fractions ( $\varphi_0$ ) were approximately 0.081 (mass density of the dry polymer = 1.129 g/cm<sup>3</sup>). We preliminarily checked the validity of the calculation method for the polymer volume fraction. The corresponding volume fraction was above the overlapping polymer volume fraction (=0.035). To control the reaction rate, the ionic strength of the buffers was 100 mM.

### Fabrication of doubly crosslinked gel

The two solutions were mixed, and the resulting solution was poured into a silicon tube with  $d_0 = 1$  mm. (i) When a certain time ( $t_i = 720, 1000, 1200, 1370, 1800, 1980, 3180, 5490,$  and  $7830$  s) passed after the gelation reaction was started, the tube was stretched with an elongation ratio  $\lambda_i = 2.6$ . (ii) When a certain time ( $t_i = 1800$  s) passed after the mixing was started, the tube was stretched with elongation ratios  $\lambda_i = 1.5, 1.9,$  and  $2.6$ . At least 12 h were allowed to pass for the reaction to complete in the stretched state.

### Fabrication of p-tuned tetra-PEG gels

Equal amounts of Tetra-PEG-NH<sub>2</sub> (20k) and Tetra-PEG-OSu (20k) ( $\varphi_0 = 0.081$ ) were dissolved in phosphate buffer (pH 7.4) and phosphate-citric acid buffer (pH 5.8), respectively. The Tetra-PEG-OSu solution was incubated at 25 °C for 0, 20, 80, and 240 min. After the incubation time, the Tetra-PEG-NH<sub>2</sub> and Tetra-PEG-OSu solutions were mixed, and the resulting solution was poured into the mold. At least 12 h were allowed for the completion of the reaction before the following experiment was performed. The corresponding reaction conversions, which were measured by infrared spectroscopy, ranged from 0.68 to 0.92.

### Uniaxial stretching and compression

A uniaxial stretching measurement was carried out in air using a mechanical testing apparatus (Autograph AG-X plus; Shimadzu, Kyoto, Japan) at a crosshead speed of 60 mm/min. The lengths of the tensile samples ranged from 12 mm to 139 mm. The corresponding strain rates ranged from 0.083 to 0.0072 s<sup>-1</sup>. The stretching measurements of the doubly crosslinked networks with various  $t_i$  values and of the  $p$ -tuned tetra-PEG gels were performed. In addition, for the tetra-PEG gel with  $p = 0.92$ , a uniaxial compression test was carried out using a mechanical testing apparatus (Instron 3365, Instron Corp.) at a velocity of 0.50 mm/min. The initial height of the compression samples was 7.5 mm.

The corresponding strain rate was 0.00011 s<sup>-1</sup>. The obtained stress-elongation relationships corresponded to the equilibrium relationships without time effects, because no appreciable relaxation in stress was observed after imposing constant strain at this crosshead speed.

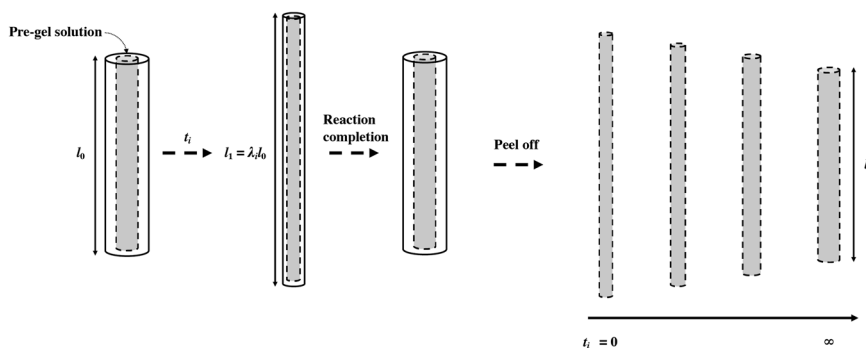
## Results and discussion

### Doubly crosslinked gel and two-network theory

We first explain the overview of the fabrication method of doubly crosslinked gel and the prediction of the two-network theory. A schematic illustration of the experimental procedure is shown in Fig. 1. The pregel solution was poured into soft silicone tubes with length ( $l_0$ ). When a particular time ( $t_i$ ) passed after the initiation of the gelation reaction, the silicone tube and gelling solution inside were stretched to  $l_1 = \lambda_i l_0$ . The gelling solution adhered to the surface of the silicone tube and deformed in the same manner as the silicone tube. According to the two-network theory, the network structure formed before  $t = t_i$  is called “the first network”. The silicone tube was kept stretched until the completion of the reaction. For time  $t > t_i$ , an additional network was formed at the deformed state ( $\lambda = \lambda_i$ ), which is called “the second network”. Notably, the first and second networks coexist in a polymer network and are covalently bonded with each other, which is different from double-network gels. The difference between the first and second networks is the state of preparation; the first network is formed at  $\lambda = 1$ ; on the other hand, the second network is formed at  $\lambda = \lambda_i$ . When the samples were peeled off from the tube, the first network shrinks, and the second network competes against the shrinkage of the first network. As a result of the balance of internal tensions, the length of the gel becomes  $l_s = \lambda_s l_0$  ( $l_0 < l_s < l_i$ ). Here, there are two extreme cases where we do not need to consider the balance of internal stresses:  $t_i = 0$  or  $\infty$ . At  $t_i = 0$ , the gelation reaction naturally occurs in a stretched silicone tube. Thus, only the second network exists, and  $l_s = l_i$ . On the other hand, at  $t_i = \infty$ , the gelation reaction is completed before the stretching, and the reacted gel inside the silicone tube is merely stretched. In this case, only the first network exists, and  $l_s = l_0$ . In the intermediate time scale, the length of the obtained samples decreases with increasing  $t_i$ , because the internal tension originating from the first networks increases with increasing  $t_i$ . As a result, when the entire polymer network is relaxed, the first network is stretched to  $\lambda_s$ , and the second network is compressed to  $\lambda_s/\lambda_i$ .

According to the two-network theory developed by Berry et al. and Flory [9, 15], the elastic free energy ( $W$ ), which is the energy stored when the system is deformed, for the doubly crosslinked gel is merely expressed as the sum of

**Fig. 1** Schematic illustration of the doubly crosslinked gel formation



the individual contributions of the first and second networks (Eq. 1). Here, we assume that the  $W$  for each network is expressed according to the classical rubbery theory following previous works [18–21, 43],

$$W = \frac{G}{2} (\lambda_x^2 + \lambda_y^2 + \lambda_z^2 - 3), \quad (2)$$

where  $G$  is the shear modulus and  $\lambda_j$  ( $j = x, y, z$ ) is the stretching ratio of the polymer network relative to a network at ease. Under uniaxial stretching ( $\lambda_x = \lambda$ ,  $\lambda_y = \lambda_z = \lambda^{-1/2}$ ), Eq. 2 can be rewritten as

$$W = \frac{G}{2} (\lambda^2 + 2\lambda^{-1} - 3) \quad (3)$$

We note that  $\lambda$  in Eq. 3 is defined as the deformation referenced to the condition of ease of the entire polymer network; the effective deformation ratios of the first and second networks are different from  $\lambda$ . Instead, the net elongation ratios of the first and second networks are described as  $\lambda_s \lambda$  and  $(\lambda_s/\lambda_i)\lambda$ , respectively. As a result,  $W_1$  and  $W_2$  are expressed as

$$W_1 = \frac{g_1}{2} \{ (\lambda_s \lambda)^2 + 2(\lambda_s \lambda)^{-1} - 3 \} \quad (4a)$$

$$W_2 = \frac{g_2}{2} \left( \left( \frac{\lambda_s}{\lambda_i} \lambda \right)^2 + 2 \left( \frac{\lambda_s}{\lambda_i} \lambda \right)^{-1} - 3 \right) \quad (4b)$$

Here,  $g_1$  and  $g_2$  represent the virtual shear moduli of the first and second networks, respectively, when they were formed independently in the undeformed states. The stress-elongation relationships are expressed as the first derivation of  $W$  with respect to  $\lambda$ :

$$\sigma = \frac{\partial W}{\partial \lambda} = \frac{\partial W_1}{\partial \lambda} + \frac{\partial W_2}{\partial \lambda} \quad (5)$$

Here, the stresses attributed to the first and second components are expressed as

$$\sigma_1 = \frac{\partial W_1}{\partial \lambda} = g_1 \lambda_s \{ (\lambda_s \lambda) - (\lambda_s \lambda)^{-2} \} \quad (6a)$$

$$\sigma_2 = \frac{\partial W_2}{\partial \lambda} = g_2 \lambda_s \left\{ \left( \frac{\lambda_s}{\lambda_i} \lambda \right) - \left( \frac{\lambda_s}{\lambda_i} \lambda \right)^{-2} \right\} \quad (6b)$$

In a network at ease, the contributions from the first and second networks are just balanced ( $\sigma_1 + \sigma_2 = 0$ ), and  $\lambda_s$  is expressed as

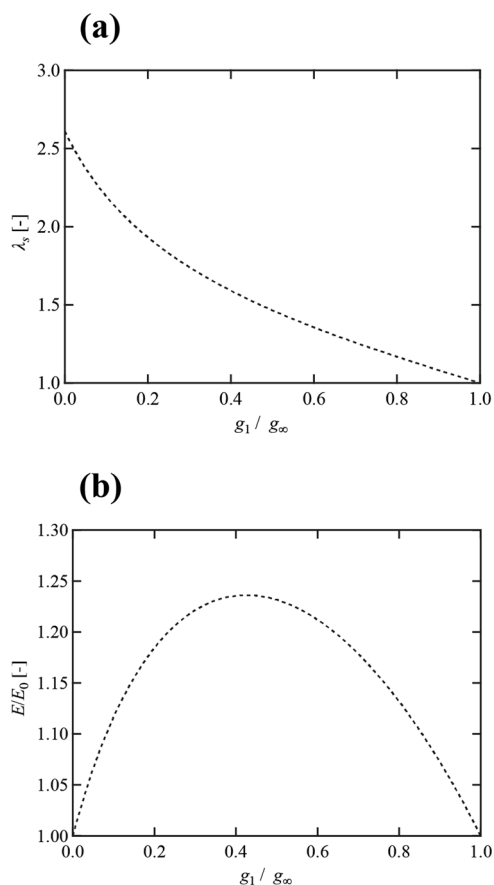
$$\lambda_s = \left\{ \frac{\lambda_i^3 - 1}{(g_1/g_2)\lambda_i^2 + 1} + 1 \right\}^{1/3} \quad (7)$$

On the other hand, the Young's modulus of the doubly crosslinked gels, which corresponds to the slope of the stress-elongation curve when the sample is stretched from the state at ease, is expressed as the second derivation of  $W$  with respect to  $\lambda$  as

$$E = \left[ g_1 \lambda_s^2 (1 + 2\lambda_s^{-3}) + g_2 \left( \frac{\lambda_s}{\lambda_i} \right)^2 \left\{ 1 + 2 \left( \frac{\lambda_s}{\lambda_i} \right)^{-3} \right\} \right] \quad (8)$$

In this study,  $g_1$  was estimated as the shear modulus at  $t_i$ , and  $g_\infty$  was estimated as the shear modulus of the gel formed in the undeformed state. The values of  $g_1$  and  $g_\infty$  are proportional to the numbers of active chains in the first network and the whole network, respectively. Thus, the virtual modulus of the second network ( $g_2$ ) was determined according to the equation,  $g_\infty = g_1 + g_2$ . Figure 2 shows the theoretical predictions of  $\lambda_s$  and  $E$  as a function of  $g_1/g_\infty$  based on Eqs. 7 and 8, respectively. Here, we set  $\lambda_i = 2.6$  as a fixed parameter fit to our experimental condition. The Young's modulus was normalized by that of the whole undeformed network ( $E_0$ ).  $\lambda_s$  monotonically decreased from 2.6 to unity with increasing  $g_1/g_\infty$ , qualitatively agreeing to the above discussion.

Additionally,  $E/E_0$  shows a maximum value at  $g_1/g_\infty \approx 0.43$ . Evidently, we can predict that  $E/E_0 = 1$  at  $t_i = 0$  or  $\infty$  because only the second or first network exists, and no internal tension is induced. For intermediate  $t_i$ , a certain extent of crosslinking was formed in the nondeformed state, and further crosslinking was formed in the stretched state, resulting in enhanced elastic modulus ( $E/E_0 > 1$ ). This

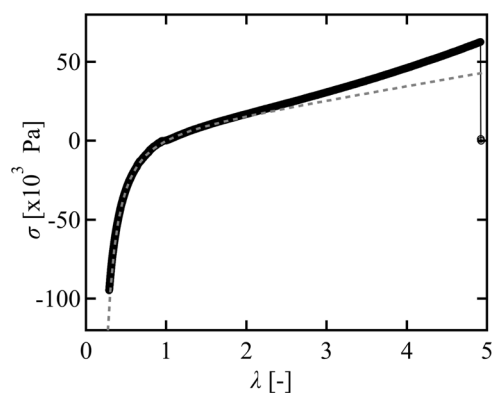


**Fig. 2** Theoretical prediction of **a** the residual strain ( $\lambda_s$ ) and **b** Young's modulus ( $E$ ) of the doubly crosslinked networks. The Young's modulus is normalized by that of the pure network

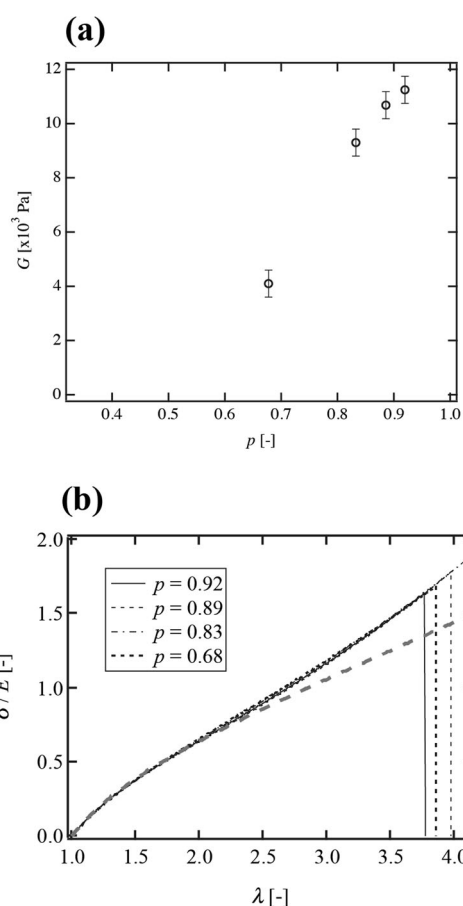
enhancement is caused by the decreased entropy of doubly crosslinked gels. The anisotropy of the first network remains frozen by the second network, because the latter, which is isotropic in the deformed state, precludes the relaxation of the former.

### Effect of reaction conversion on mechanical properties of the tetra-PEG gel

To experimentally examine the two-network theory, the  $W$  function of the model network should be well known and robust against gelation reaction conversion ( $p$ ). Figure 3 shows the stress-elongation curve for the tetra-PEG gel with  $p = 0.92$ . The data with  $\lambda < 1$  and  $\lambda > 1$  correspond to those for compression and elongation, respectively. The red line represents the prediction of the classical rubber theory (Eq. 3) [18–21]. The experimental results well agree with the theoretical prediction within a moderate strain region. We should note that the upward deviation for a large deformation region is attributed to the finite extensibility of the network strands, as discussed previously [42]. In this paper, the maximum  $\lambda_i$  was set to 2.6 to minimize the effect of the finite extensibility.

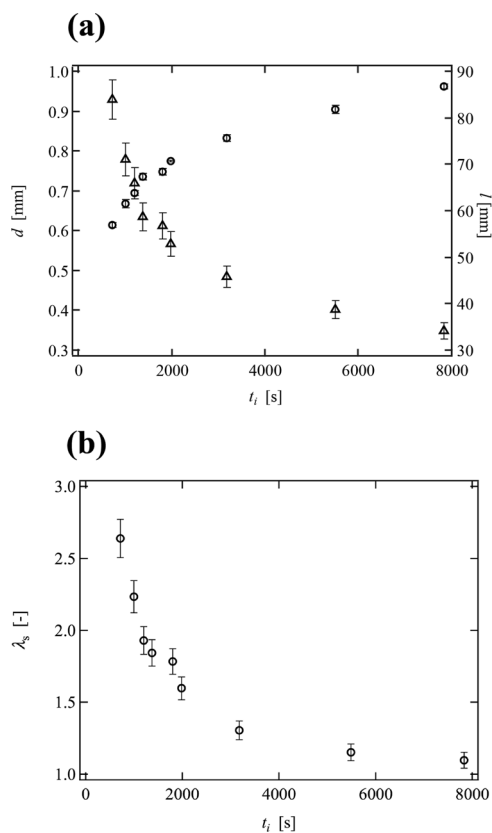


**Fig. 3** Stress-elongation curve for the tetra-PEG gel. The red line represents the prediction of the classical rubber theory (color figure online)



**Fig. 4** **a** Stress-elongation curves of the  $p$ -tuned tetra-PEG gels. **b** shear modulus against  $p$ . **c** Stress-elongation curves normalized by the Young's modulus. The dashed line represents the prediction of the classical rubber theory

Figure 4a shows the Young's modulus of the tetra-PEG gels with  $p = 0.68$ – $0.92$ . The variation in  $p$  from 0.92 to 0.68 resulted in tuning  $g_1/g_\infty$  from 1.0 to 0.05. This change occurred because the active chains are formed beyond the gelation threshold ( $p \sim 0.4$  for the tetra-PEG gel) and the number of the

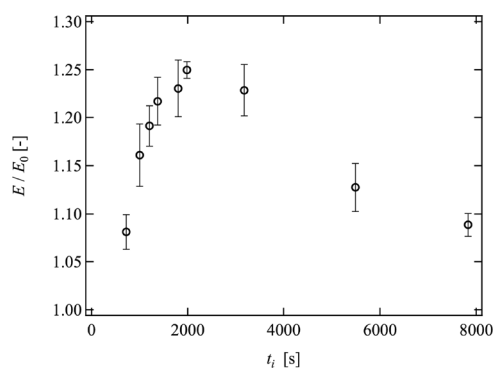


**Fig. 5** **a** Diameter (circles) and length (triangles) of the samples **b** permanently set for the doubly crosslinked gels against  $t_i$

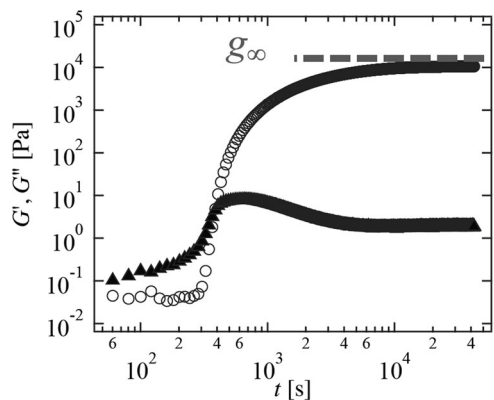
active chains does not increase linearly with increasing  $p$ . The increasing rate is more rapid at the low  $p$  region than that at the high  $p$  region, which can be explained by the Bethe approximation written in ref. [44]. Figure 4b shows the stress-elongation curves normalized by  $E$ . The dashed line represents the prediction of the classical rubber theory. All the experimental curves overlap each other, suggesting that connectivity has a limited impact on the finite extensibility within the region of  $p$  examined. In other words, the connectivity ( $p$ ) and the network strand length ( $N$ ) are decoupled as reported previously [42]. In addition to this finding, the curves well agree with the prediction of the classical rubber theory in the region  $\lambda < 2.5$ . According to these experimental results, we conclude that the tetra-PEG gel system has a robust  $W$  function obeying the classical rubber theory.

### Effect of time for imposition of the stretching on the gels during the gelation reaction

We prepared a series of doubly crosslinked networks using the tetra-PEG gel system ( $l_0 = 1.0$  mm,  $d_0 = 32$  mm,  $\lambda_i = 2.6$ ). Figure 5a shows the diameter ( $d$ ) and length ( $l$ ) for the doubly crosslinked gels against  $t_i$ . As  $t_i$  increased,  $d$  decreased, and  $l$  increased. Figure 5b shows the  $t_i$ -dependence of the residual strain ( $\lambda_s$ ).  $\lambda_s$  decreased with



**Fig. 6** Normalized Young's modulus for the doubly crosslinked gels against the stretching time ( $t_i$ )

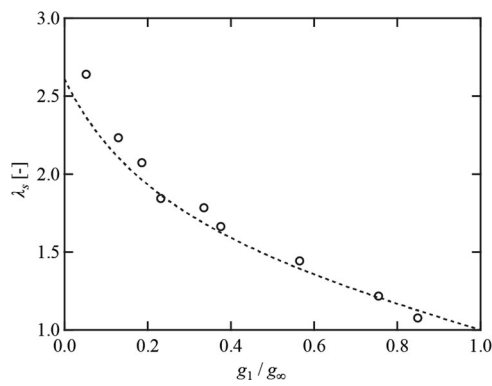


**Fig. 7** Time development of the storage ( $G'$ , circles) and loss ( $G''$ , triangles) moduli during the gelation reaction

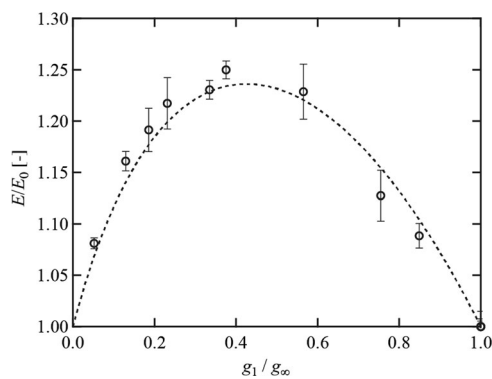
increasing  $t_i$  and asymptotically approached unity from 2.6. Figure 6 shows the Young's modulus ( $E$ ) for the doubly crosslinked gels against  $t_i$ . All the data were normalized by the modulus of the unstretched gel ( $E_0$ ). The  $E/E_0$  value increased with increasing  $t_i$ , reached a maximum value at  $t_i = 1980$ , and then decreased to unity. These results qualitatively corresponded to the prediction of the two-network theory.

To experimentally estimate the value of  $g_1/g_\infty$ , we performed an oscillatory measurement during the gelation reaction for the network "at ease" and obtained the relationships between the storage modulus ( $G'$ ) and the reaction time, as shown in Fig. 7. Prior to the experiments, we had checked that  $g_1$  and  $g_\infty$  corresponded to the value of the plateau modulus and had little frequency dependence. Figure 8 shows the relationships between  $\lambda_s$  and  $g_1/g_\infty$  with the prediction of Eq. 7 (dashed line). The two-network theory well reproduced the experimental results. Furthermore, the normalized Young's modulus was well reproduced by the prediction of Eq. 8 (Fig. 9). Based on these results, we confirmed the validity of the two-network theory in the case of the constant stretching ratio.





**Fig. 8** Residual strain for the doubly crosslinked gels against the ratio of the first network component ( $g_1/g_\infty$ )



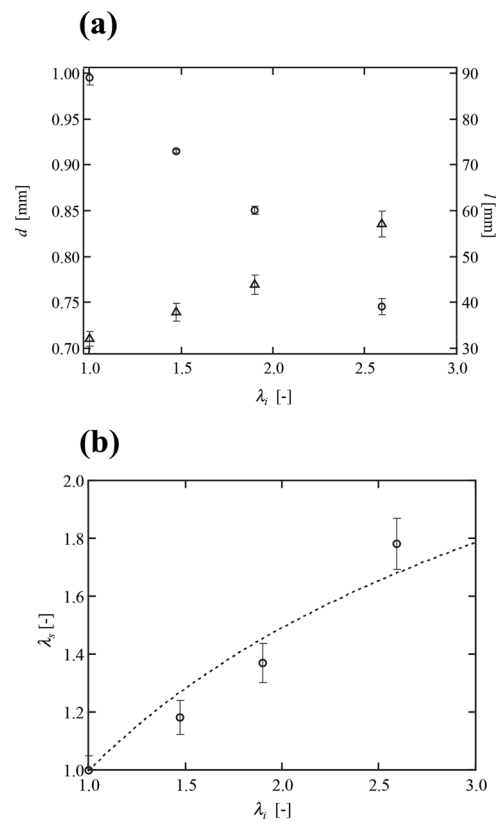
**Fig. 9** Normalized Young's modulus for the doubly crosslinked gels against the ratio of the first network component ( $g_1/g_\infty$ )

### Effect of the stretching ratio

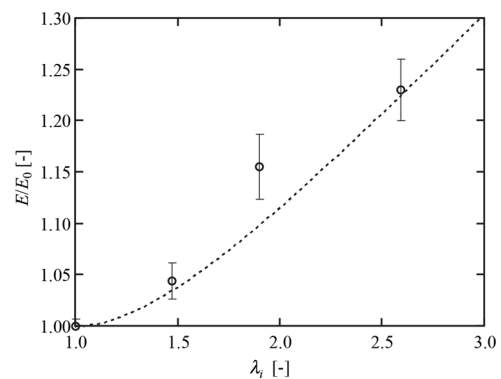
In the previous section, we changed the fraction of the first network by tuning  $t_i$ . Here, we changed the imposed stretching ratio ( $\lambda_i$ ) with maintaining  $t_i = 1800$  s, which resulted in tuning  $\lambda_i$  with a constant  $g_1/g_\infty$ . As shown in Fig. 10a,  $d$  decreased, while  $l$  increased with increasing  $\lambda_i$ . As a result,  $\lambda_s$  monotonically increased with increasing  $\lambda_i$  (Fig. 10b). The prediction of Eq. 7 (dashed line) well reproduced the experiments as well. Good agreement was also observed for the normalized Young's modulus and prediction of Eq. 8 (Fig. 11). These results strongly suggest that the two-network theory is valid for the chemically crosslinking-dominant networks and that the simple sum rule of the strain energy density function is reasonable to describe the mechanical properties of anisotropic materials.

### Conclusion

In this study, we fabricated doubly crosslinked networks using the tetra-PEG gel with near-ideal network structures. We investigated the Young's modulus and residual strain as



**Fig. 10 a** Diameter (circles) and length (triangles) of the samples and **b** residual strain for the doubly crosslinked gels against  $\lambda_i$ . The dashed line represents the prediction of Eq. 7



**Fig. 11** Normalized Young's modulus for the doubly crosslinked gels against the stretching ratio ( $\lambda_i$ )

a function of the time for the imposition of the stretching of the gels ( $t_i$ ) and the stretching ratio ( $\lambda_i$ ) during the gelation reaction. The results showed that (1) the residual strain decreased with increasing  $t_i$ ; (2) the Young's modulus had a maximum value accompanied with  $t_i$ ; and (3) the Young's modulus and the residual strain increased with increasing  $\lambda_i$ . These results are quantitatively reproduced in the framework of the two-network theory, which models the balance of strain energy between the first and second networks.

Based on these observations, we for the first time succeeded in quantitatively validating the two-network theory.

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## Compliance with ethical standards

**Conflict of interest** The authors declare that they have no conflict of interest.

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