Polymeric nanofibers: isodiametric design space and methodology for depositing aligned nanofiber arrays in single and multiple layers

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INTRODUCTION

Polymeric micro/nanofibers are increasingly gaining importance due to their versatile applications in diverse fields, such as tissue engineering, smart textiles, sensors and actuators. Traditionally, the well-established techniques of spun bounding,^{1,2} melt blowing,^{3,4} dry spinning,^{5,6} conjugate spinning⁷ and CO₂ laser thinning⁸ produce polymeric fibers with diameters on the micron scale and lengths in excess of a meter. However, aligned deposition and continuous production of long fibers with nanoscale diameters has been a challenge due to the fragility of polymeric materials. In addition, numerous applications require the deposition of smooth, uniform and defect-free nanofiber arrays in aligned configurations with user-defined geometrical spacing. Several processes have been developed to fabricate polymer nanofiber arrays, including electrospinning,^{9–13} template synthesis,^{14,15} phase separation^{16,17} and sequential micro dry spinning.¹⁸ Of all these methods, electrospinning is perhaps the most popular process, allowing for the continuous production of fibers ranging from tens of nanometers to a few microns in diameter and requiring specialized strategies for the aligned deposition of these fibers.19-24

Although nanofibers can be essentially aligned in single and multiple layers, tight control over the fiber diameter and spacing has yet to be realized. The deficiencies of the current state-of-the-art fabrication methods continue to hinder improvements in the applications of polymer nanofibers. Here, we present a non-electrospinning strategy based on our previously reported STEP (Spinneret based Tunable Engineered Parameters) technique²⁵ to deposit arrays of polymer fibers with uniform diameters ranging from sub-100 nm to microns and lengths of at least several millimeters. In addition, this strategy has the ability to control adjacent fiber-fiber spacing. The control of fiber diameter is achieved by manipulating the polymer chain entanglements in the polymer-solvent solution, which are directly related to the polymer solution concentration and the molecular weight. The molecular entanglement-fiber diameter relationships are mapped to obtain an isodiametric design space, which provides a convenient visual tool for estimating the fiber diameters. Furthermore, nanofiber assemblies in single and multiple layers are demonstrated using isodiametric fibers as building blocks, which helps to establish a much needed, robust engineering framework for depositing aligned micro/nanofibers in hierarchical assemblies.

EXPERIMENTAL PROCEDURE

Solution preparation

All chemicals were used as received without further purification. Polystyrene (PS) of several molecular weights (M_W) (650, 860, 1500 and 2000 K g mol⁻¹, Scientific Polymer Products Inc., Ontario, NY, USA) were dissolved at room temperature in p-xylene with varying wt% concentrations (from 1 wt to 18 wt%) for 1 week before experiments. Poly(methyl methacrylate) (PMMA, $M_W = 540$ Kg mol-1, Scientific Polymer Inc., Ontario, NY, USA) dissolved in chlorobenzene at 14 wt% and poly(lactic-co-glycolic acid) (PLGA, Purac Biochem, Gorinchem, Holland) dissolved in chloroform at 3 wt% were used in this study. Bovine plasma fibrinogen (Sigma-Aldrich Chemical, St Louis, MO, USA) was dissolved in a solution composed of 9 parts 1,1,1,3,3,3-hexafluoro-2propanol and 1 part 10 × minimal essential medium at 20 wt% for 1 week before experiments. Polyurethane (PU5719, Lubrizol Advanced Material, Wickliffe, OH, USA) was dissolved in dimethylformamide at 30 wt% and heated to $80\,^\circ C$ with stirring for $24\,h$ to prepare a homogenous solution. One gram of titanium isopropoxide (Ti(O*i*Pr)₄, Sigma-Aldrich Chemical) was mixed with 2.7 g of a 7 wt% PS ($M_W = 2000$ K)-xylene solution, followed by magnetic stirring for 1 h before experiments.

STEP spinning

The spinning process was performed at a temperature of 20 °C and a relative humidity of 13–17%. The viscous polymer solutions were pumped through the micropipette spinneret ($ID = 100 \,\mu$ m) and formed an extruded solution droplet at the exit (Figure 1a). The substrate was mounted on a DC motor, which, in turn, was mounted on a motorized micro-positioning stage with three degrees of freedom (VP-25XA, Newport Inc., Stanta Clara, CA, USA). After the substrate made contact with the solution droplet, the fibers were collected on the substrate in aligned configurations. No voltage source was used in the experiments to eject the polymer solution.

Solvent treatment

A fused PMMA fiber network was obtained by exposing the PMMA fiber assembly to chlorobenzene vapor at room temperature in an enclosed chamber for 20 s.

Calcination

As-spun PS-titanium isopropoxide fibers were left in air for 4 h to allow for the complete hydrolysis of Ti(O*i*Pr)₄. PS was removed by treating the fibers in air at 750 °C for 4 h.

Fiber dyeing

Fluorescent reagents DiT (Red), DiD (Purple) and DiC (Green) (Biotium Inc., Hayward, CA, USA) were dissolved in dimethyl sulfoxide at 1 mg ml⁻¹, and the solutions were sonicated for 5 h at 50 °C. For the fiber staining process, 1 μ l of fluorescent reagent solution was added to 1 ml polymer solutions, and the mixture was further sonicated for 1 h before spinning.



Figure 1 (a) A schematic illustration of the experimental set-up of the STEP technique; (b) an optical image of the fiber formation process with the edge of the rotating substrate represented by the dashed line. A full color version of this figure is available at *Polymer Journal* online.



Figure 2 The linear regression analysis developed for the fiber diameter vs (a) the normalized concentration (C/C^*), (b) the molecular weight and (c) the isodiametric design space for the PS nanofibers superimposed on the Graessley diagram:²⁷ the blue lines represent isodiametric lines, and the numbers on these lines denote the fiber diameters. Inserts 1–4 are representative images corresponding to the four points (noted as 1–4) in the design space. Each data point in **a** and **b** is an average result of at least 50 measurements. A full color version of this figure is available at *Polymer Journal* online.

All measurements were performed at room temperature. The intrinsic viscosity and the Mark–Houwink–Sakurada constants were obtained through dilute solution viscometry experiments (Supplementary Information, SI1). Field-emission scanning electron microscopy studies were conducted using an FEI Quanta 600 microscope working at 5–25 kV. Fluorescent images were taken with an Axio Observer (Carl Zeiss Microimaging Inc., Thornwood, NY, USA). Optical images were taken with an AmScope 800 digital camera attached to a \times 30 microscope (Carl Zeiss Microimaging Inc.).

RESULTS AND DISCUSSION STEP-based fiber fabrication

The STEP technique requires an ambient atmosphere to evaporate the solvent, leading to the formation of a solid fiber, but more importantly, the technique does not require the aid of an electric field, as is the case with electrospinning. As shown in Figure 1b, a micropipette loaded with polymer solution is connected to a pressure source, which results in an extruded polymer solution droplet at the tip of the micropipette. A rotating substrate is brought into contact with the solution droplet, thus pulling out a single *filament*. During the stretching process of the solution filament, continual evaporation of the solvent causes an increase in molecular entanglements, thereby reducing the overall deformability. A solidified fiber is formed by rapid solvent evaporation and collected on the substrate in an aligned configuration. In contrast to electrospinning, which relies on an electric field, STEP relies on the rotating speed of the substrate to 'stretch and thin' the solution filament. We emphasize that for the STEP technique, the fluid filament is pulled out, rather than ejected, from the tip of the droplet and thus resembles a fluid element being pulled out from an endless reservoir. As no voltage is involved, the fluid jet whipping and spraying present in other methods are avoided in STEP manufacturing, resulting in parallel fiber arrays with narrow fiber diameter distributions.

Using the STEP technique, hierarchical fiber assemblies are easily achieved by depositing fiber arrays on top of previous layers at desired angles with user-defined fiber spacing. High aspect ratio fibers of long lengths (mm-cm) with diameters ranging from sub-100 nm to microns (length/diameter aspect ratio > 2000) were obtained by optimizing the processing parameters (rotating speed of the substrate) and material parameters (solution concentration and

polymer molecular weight). We have previously reported that an increase in the rotational speed of the substrate (V_r) leads to a decrease in the fiber diameter and that, for speeds exceeding 1 m s⁻¹, constant diameter fibers were obtained.25 Furthermore, we also reported an increase in the fiber diameter with increased polymer solution concentration. In this study, we present an engineered design space at constant V_r $(1.2 \,\mathrm{m\,s^{-1}})$ for fabricating uniform diameter fibers (70-800 nm) with high aspect ratios (>2000). The isodiametric design space for fabricating continuous fibers is dependent upon achieving a minimum number of polymeric molecular chain entanglements for different molecular weights. The entanglements in a polymer solution are typically represented by critical overlap concentrations (C^*) and critical entangled concentrations (Ce) (Supplementary Information, SI1).

Isodiametric design space

PS was dissolved in *p*-xylene with increasing concentrations at four molecular weights (650, 860, 1500 and 2000 K g mol⁻¹). The diameter dependence on the solution concentration (*C*) was then investigated (Figure 2a) and was

found to scale with C^* as:

550 K: Dia(nm) =
$$0.3 \left(\frac{C}{C^*}\right)^{2.1}$$
 (1)

860 K: Dia(nm) =
$$2.9 \left(\frac{C}{C^*}\right)^{1.4}$$
 (2)

1500 K : Dia(nm) =
$$10.3 \left(\frac{C}{C^*}\right)^{1.1}$$
 (3)

2000 K: Dia(nm) =
$$60.7 \left(\frac{C}{C^*}\right)^{0.7}$$
 (4)

The scaling laws were developed using C^* , as the critical overlap concentrations were accurately obtained from the dilute solution intrinsic viscosity experiments. Similarly, the diameter dependence on the molecular weight for different concentrations was investigated (Figure 2b) and found to scale as:

- 10% wt: Dia(nm) = $1E 9(M_w)^{1.8}$ (5)
- 14% wt : $\text{Dia}(\text{nm}) = 4\text{E} 8(M_w)^{1.6}$ (6)

$$18\%$$
 wt : Dia(nm) = $8E - 5(M_w)^{1.1}$ (7)

As evidenced by Equations (1)–(4), the lower molecular weight species exhibit higher exponents, which demonstrates that a higher concentration is required for the formation



Figure 3 Bottom-up PS nanofiber assemblies using STEP: (a) 70 nm fiber arrays on top of a 800 nm diameter fiber; (b) 800 nm diameter fiber arrays in orthogonal configurations; (c) three layers of fiber arrays configured at 60° angles with each other with $d_1 = d_2 = 400$ nm, $d_3 = 800$ nm; and (d) a hierarchical fiber assembly of different diameter fibers with controlled orientations and $d_1 = 400$ nm, $d_2 = 800$ nm, $d_3 = d_4 = 70$ nm; $\alpha_{12} = \alpha_{23} = 80^\circ$, $\alpha_{34} = 90^\circ$.

of the polymer chain entanglements necessary to form smooth and uniform fibers. In Equations (5)–(7), the decreasing exponents demonstrate the diminishing role of molecular weight in the fiber formation process as the concentration increases, which can be explained through the relationship between the gyration radius of the polymer chain (R_G) and the polymer solution concentration (C): $R_G \sim C^{-1/4}$.²⁶ An increase in the polymer solution concentration makes the polymer chains in solution more compact, thus limiting the effect of the molecular weight.

The role of increased polymer chain entanglements with an increase in (i) the molecular weight (at the same concentration) and (ii) the concentration (at the same molecular weight) is to restrict the ability of individual polymeric chain segments to undergo physical deformation in the extensional stress field during the fiber formation process. The scaling laws developed for the fiber diameter control (Equations (1)-(7)) are mapped to obtain the Isodiametric design space (Figure 2c). Through visual inspection of the isodiameter lines (blue lines) in the mapped design space, determining the regions of solution rheology with sufficient polymer chain entanglements for the fabrication of smooth, uniform fibers with diameters ranging from 70 to 800 nm and lengths of at least several millimeters is straightforward. The STEP-based uniform diameter fiber arrays were obtained at concentrations closer to and greater than C_e (Supplementary Information, SI Table 1), which indicates the transition from the semi-dilute unentangled domain to the semi-dilute entangled domain. At Ce, the molecular chains are considered to have sufficient overlaps, thus forming a long-range physical entanglement network, which is necessary for the continuous fabrication of smooth and uniform fibers. An increase in the concentration beyond Ce leads to compacted polymeric chains due to a decreased number of solvent molecules entrapped in the entangled polymer chain networks, which ultimately results in larger diameters under the same external extensional stress.

The limiting cases for the formation of fibers with acceptable attributes (smooth, defect-free and of substantial length) occur at solution rheologies with very high and very low concentrations. At low concentrations (semi-dilute un-entangled and dilute domains), there are not enough polymer molecules to form long-range networks, yielding the classic beaded morphology as shown in insert 1 (corresponding to point 1 in the design space). At the other extreme of highly concentrated rheologies, the absence of solvent molecules leads to the convergence of isodiameter lines, indicating the limits of dry-spinning-based manufacturing methods, such as STEP and electrospinning. At these high concentrations, fibers of large diameters (tens of microns) were obtained along with fiber beads, as shown in insert 4 (corresponding to point 4 in the design space); these fibers are comparable to those obtained from traditional melt-spinning manufacturing methods.^{28–30}

Fibers of increasing diameters were obtained through the transition of solution rheologies from semi-dilute to concentrated regimes. As shown in Figure 2c inserts 2 and 3, aligned 70 nm diameter fiber arrays were obtained in the semi-dilute entangled region (point 2), while 500 nm diameter fiber

arrays were obtained in the concentrated entangled region (point 3). The fiber diameter distribution is well controlled within 20%, including any manufacturing and measurement errors (Supplementary Information, SI2).

Nanofiber assemblies based on STEP

Manipulating nanofibers into patterns/ assemblies is of great interest because of their potential application in sensors, bioimplantations and smart textiles. Intensive efforts have been devoted to achieving nanofiber assemblies and patterns using electrospinning,^{31–33} direct drawing³⁴ and rotary jet-spinning.³⁵ Using these approaches, nanofiber assemblies in the form of unidirectional arrays, cross-bars and stacked membranes have been created; however, the uniformity of constituent nanofiber dimensions and



Figure 4 Fiber assemblies made from various materials: (a) suspended unidirectional PU fibers with the scale bar in the insert representing $25 \,\mu$ m; (b) evenly spaced unidirectional fibrinogen fibers; (c) a PLGA fiber assembly with top and bottom layers configured at a 50° angle; (d) an inter-connected orthogonal PMMA fiber network; (e) an assembly incorporating PU fibers (green), PS (red) and PLGA fibers (purple); and (f) an array of densely packed uniform diameter titanium dioxide fibers.

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inter-fiber spacing was difficult to control. In contrast to these approaches, STEP is capable of generating nanofiber assemblies with unique control of the fiber dimensions, spacing and orientations. Uniform diameter STEP fibers are configured in parallel arrays as they are collected on substrates, whereas the space between fibers is easily controlled by adjusting the substrate translation speed. At constant rotational speeds, the fiber spacing is directly proportional to the translation speed. In addition, layers of fiber arrays can be deposited on top of previously deposited layers at any desired angle. Owing to the absence of an electric field, sub-100 nm diameter fibers can be easily deposited in the form of evenly spaced uniform fiber arrays without being disturbed by any spinning instabilities. In Figures 3a and b, we demonstrate 70 nm diameter fiber arrays on top of an 800 nm diameter fiber and a crisscross fiber assembly of 800 nm diameter fibers forming a matrix of rectangular unit cells. Notice that from Figures 3a to 3b, the fiber spacing was increased from 1 to 16 µm by increasing the translational speed from 0.02 to $0.32 \,\mathrm{mm}\,\mathrm{s}^{-1}$. More complex fiber patterns were achieved by stacking several layers of fiber arrays together while varying the interlaver angles. Figure 3c presents an assembly formed by three layers of fiber arrays (diameters: $d_1 = d_2 = 400 \text{ nm}, \quad d_3 = 800 \text{ nm})$ deposited at 60° angles to each other, thereby creating equilateral triangles. In addition, large diameter fiber networks can be used as the basis of the assembly, over which sub-100 nm diameter fiber networks form the top structures, resulting in a bottom-up hierarchical structure. Figure 3d shows such a hierarchical assembly, which incorporates a basis made of medium diameter fibers $(d_1 = 400)$ nm) and large diameter fibers ($d_2 = 800 \text{ nm}$) and a top structure made of small diameter fibers $(d_3 = d_4 = 70 \text{ nm})$ with controlled orientations (α_{12} , α_{23} , α_{34}) and fiber spacing.

The proposed STEP-based methodology is able to achieve nano/micro fiber arrays of various polymer species with control of the fiber diameter, spacing and orientation. Figure 4a presents a suspended unidirectional polyurethane (PU) fiber array (diameter: \sim 450 nm), whereas Figures 4b and c present fibrinogen fiber (diameter: 400-900 nm) and PLGA fiber (diameter 150-500 nm) assemblies, respectively. Figure 4d shows an interconnected PMMA fiber network composed of 3×4 equal size unit cells that was obtained by treating the crisscross PMMA fiber assembly with solvent vapor. The PMMA fibers became flat ribbons of 4-5 µm in width and were fused at intersections. Uniquely, the fibers of different species can be incorporated into a single assembly as shown in Figure 4e, where a suspended three-layer assembly is composed of three species of polymer fibers: a top layer of PLGA fibers (purple), a middle layer of PS fibers (red) and a bottom layer of PU fibers (green).

In addition, composite nanofibers consisting of inorganics and polymers can be fabricated by spinning solutions containing both PS and metal alkoxide. Calcination of aligned composite nanofibers at elevated temperature removes PS, resulting in pure ceramic fibers as indicated by the array of densely packed uniform diameter titanium dioxide fibers (diameter: ~ 400 nm) in Figure 4f. The development of precise inorganic fiber assemblies is part of our future work.

CONCLUSION

An isodiametric design space is developed to deposit PS fibers with diameters ranging from 70 to 800 nm with lengths of at least several millimeters. Molecular entanglementbased scaling laws are used to investigate the role of polymer chain entanglements on fiber formation and to demonstrate that smooth, uniform fibers of substantial length are obtained at concentrations approaching and exceeding the critical entangled concentration (C_e) . Visual inspection of the *isodiametric* design space provides knowledge of the polymer molecular weight and solution concentration rheology required to fabricate continuous high aspect ratio fibers. The design space-based assembly of fibers in three dimensions with control of the fiber dimensions and spatial deposition (including orientation and spacing) is demonstrated for multiple polymer species. The design framework outlined in this study is generalizable to inorganic material systems and establishes a much needed design framework for the highly repeatable and controllable deposition of isodiametric micro/nanofibers in a bottom-up assembly environment.

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